

UCLA STAT 110 A

Applied Probability & Statistics for Engineers

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Chapter 5: Marginal & Joint PDF's Central Limit Theorem (CLT)

- Jointly distributed RV's
- Expected Value, Covariance, Correlation
- Distributions of sample statistics
- Central Limit Theorem (CLT)

Introduction

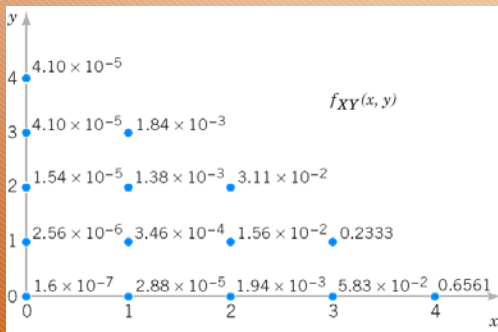
● If X and Y are two random variables, the probability distribution that defines their simultaneous behavior is a **Joint Probability Distribution**.

Examples:

- Signal transmission: X is high quality signals and Y low quality signals.
- Molding: X is the length of one dimension of molded part, Y is the length of another dimension.
- THUS, we may be interested in expressing probabilities expressed in terms of X and Y, e.g.,
 $P(2.95 < X < 3.05 \text{ and } 7.60 < Y < 7.8)$

Two discrete random variables

- **Range of random variables (X,Y)** is the set of points (x,y) in 2D space for which the probability that X=x and Y=y is positive.
- If X and Y are discrete random variables, the joint probability distribution of X and Y is a description of the set of points (x,y) in the range of (X,Y) along with the probability of each point.
- Sometimes referred to as **Bivariate probability distribution**, or **Bivariate distribution**.



Joint probability distribution

Joint probability mass function

● The joint probability mass function of the discrete random variables X and Y, denoted as $f_{XY}(x,y)$ satisfies:

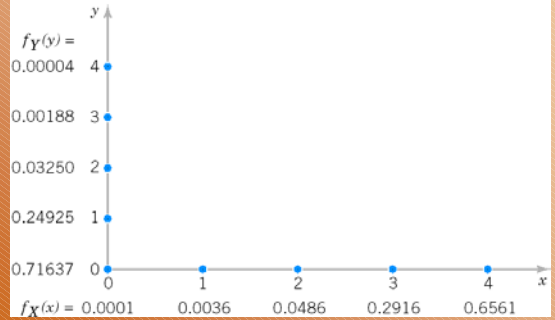
- (1) $f_{XY}(x,y) \geq 0$
- (2) $\sum_x \sum_y f_{XY}(x,y) = 1$
- (3) $f_{XY}(x,y) = P(X = x, Y = y)$

Marginal probability distributions

- Individual probability distribution of a random variable is referred to as its **Marginal Probability Distribution**.
- Marginal probability distribution of X can be determined from the joint probability distribution of X and other random variables.
- Example 5-3: **Marginal probability distribution of X is found by summing the probabilities in each column, for y, summation is done in each row.**

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Marginal probability distribution for X and Y

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Marginal probability distributions (Cont.)

- If X and Y are discrete random variables with joint probability mass function $f_{XY}(x,y)$, then the marginal probability mass function of X and Y are

$$f_X(x) = P(X = x) = \sum_{R_x} f_{XY}(X, Y)$$

$$f_Y(y) = P(Y = y) = \sum_{R_y} f_{XY}(X, Y)$$

where R_x denotes the set of all points in the range of (X, Y) for which $X = x$ and R_y denotes the set of all points in the range of (X, Y) for which $Y = y$

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Mean and Variance

- If the marginal probability distribution of X has the probability function $f(x)$, then

$$E(X) = \mu_X = \sum_x x f_X(x) = \sum_x x \left(\sum_{R_x} f_{XY}(x, y) \right) = \sum_x \sum_{R_x} x f_{XY}(x, y)$$

$$= \sum_R x f_{XY}(x, y)$$

$$V(X) = \sigma^2_X = \sum_x (x - \mu_X)^2 f_X(x) = \sum_x (x - \mu_X)^2 \sum_{R_x} f_{XY}(x, y)$$

$$= \sum_x \sum_{R_x} (x - \mu_X)^2 f_{XY}(x, y) = \sum_R (x - \mu_X)^2 f_{XY}(x, y)$$

- R = Set of all points in the range of (X, Y) .
- Example 5-4.

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Joint probability mass function – example

The joint density, $P\{X, Y\}$, of the number of minutes waiting to catch the first fish, X, and the number of minutes waiting to catch the second fish, Y, is given below.

P {X=i, Y=k}	k			Row Sum P{X=i}	
	1	2	3		
i	1	0.01	0.02	0.08	0.11
	2	0.01	0.02	0.08	0.11
	3	0.07	0.08	0.63	0.78
Column Sum P {Y=k}	0.09	0.12	0.79	1.00	

- The (joint) chance of waiting 3 minutes to catch the first fish and 3 minutes to catch the second fish is:
- The (marginal) chance of waiting 3 minutes to catch the first fish is:
- The (marginal) chance of waiting 2 minutes to catch the first fish is (circle all that are correct):
- The chance of waiting at least two minutes to catch the first fish is (circle none, one or more):
- The chance of waiting at most two minutes to catch the first fish and at most two minutes to catch the second fish is (circle none, one or more):

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Conditional probability

- Given discrete random variables X and Y with joint probability mass function $f_{XY}(X, Y)$, the conditional probability mass function of Y given $X=x$ is

$$f_{Y|X}(y|x) = f_{XY}(x, y) / f_X(x) \quad \text{for } f_X(x) > 0$$

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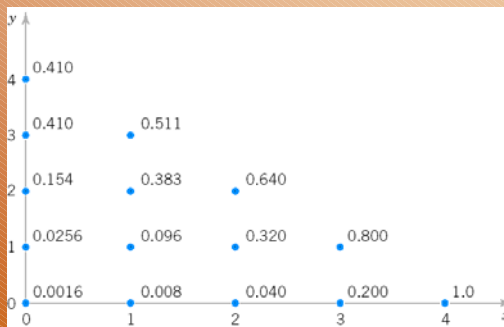
Conditional probability (Cont.)

● Because a conditional probability mass function $f_{Y|x}(y)$ is a probability mass function for all y in R_x , the following properties are satisfied:

(1) $f_{Y|x}(y) \geq 0$

(2) $\sum_{R_x} f_{Y|x}(y) = 1$

(3) $P(Y=y|X=x) = f_{Y|x}(y)$



Conditional probability (Cont.)

● Let R_x denote the set of all points in the range of (X, Y) for which $X=x$. The conditional mean of Y given $X=x$, denoted as $E(Y|x)$ or $\mu_{Y|x}$, is

$$E(Y | x) = \sum_{R_x} y f_{Y|x}(y)$$

● And the conditional variance of Y given $X=x$, denoted as $V(Y|x)$ or $\sigma^2_{Y|x}$ is

$$V(Y | x) = \sum_{R_x} (y - \mu_{Y|x})^2 f_{Y|x}(y) = \sum_{R_x} y^2 f_{Y|x}(y) - \mu_{Y|x}^2$$

Independence

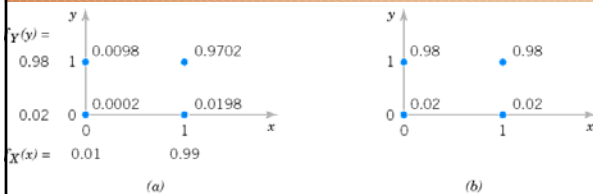
● For discrete random variables X and Y , if any one of the following properties is true, the others are also true, and X and Y are independent.

(1) $f_{XY}(x, y) = f_X(x) f_Y(y)$ for all x and y

(2) $f_{Y|x}(y) = f_Y(y)$ for all x and y with $f_X(x) > 0$

(3) $f_{X|y}(x) = f_X(x)$ for all x and y with $f_Y(y) > 0$

(4) $P(X \in A, Y \in B) = P(X \in A)P(Y \in B)$ for any sets A and B in the range of X and Y respectively.

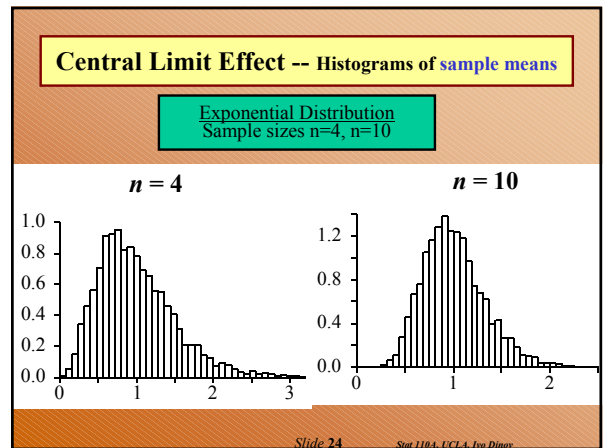
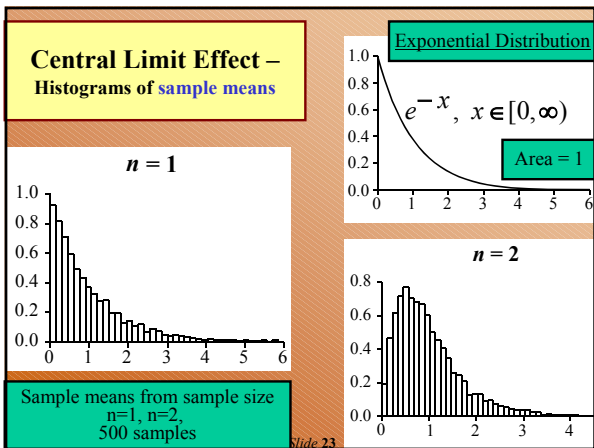
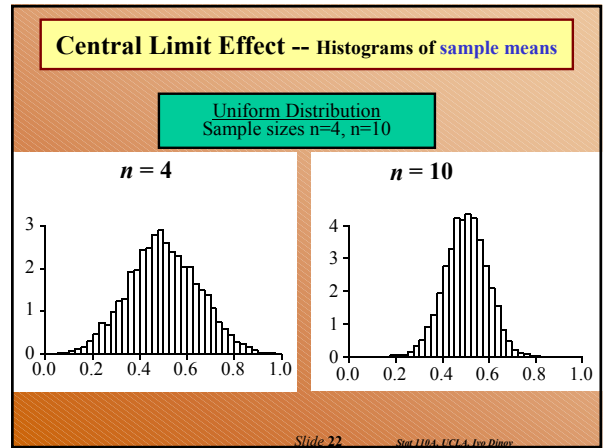
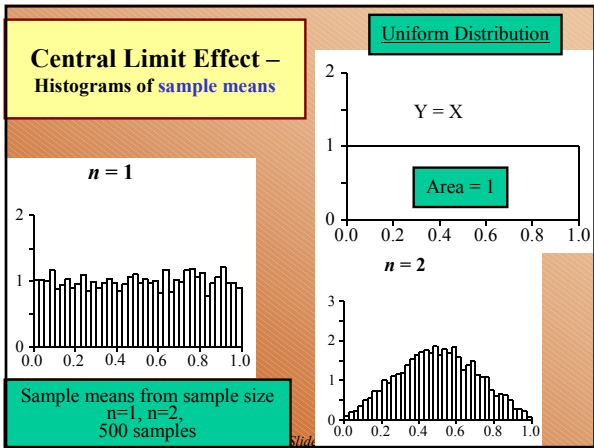
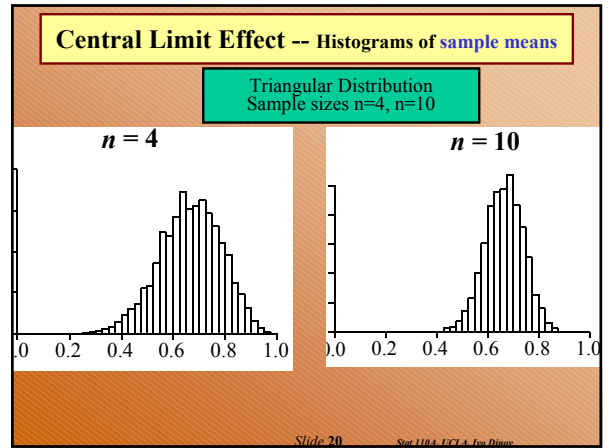
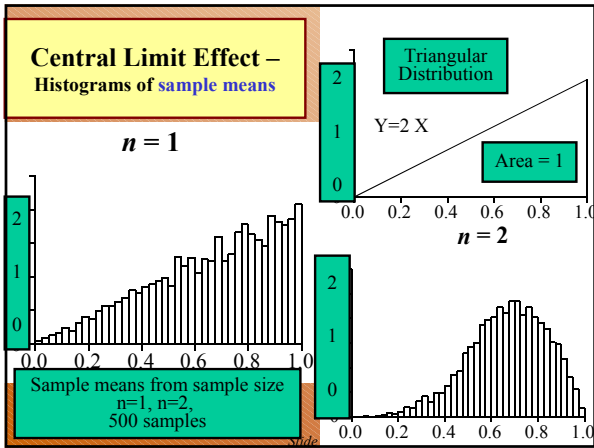


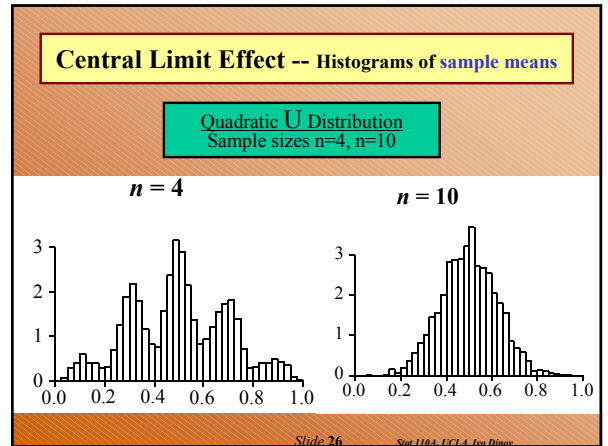
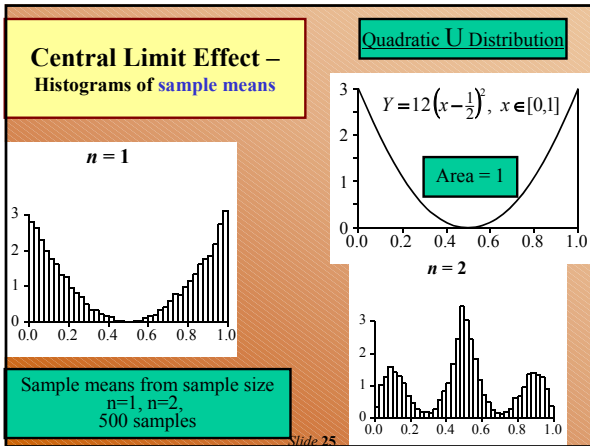
Recall we looked at the sampling distribution of \bar{X}

● For the sample mean calculated from a random sample, $E(\bar{X}) = \mu$ and $SD(\bar{X}) = \sigma/\sqrt{n}$, provided

$\bar{X} = (X_1 + X_2 + \dots + X_n)/n$, and $X_k \sim N(\mu, \sigma)$. Then

● $\bar{X} \sim N(\mu, \frac{\sigma}{\sqrt{n}})$. And variability from sample to sample in the **sample-means** is given by the variability of the individual observations divided by the square root of the sample-size. In a way, **averaging decreases variability**.





Central Limit Theorem – heuristic formulation

Central Limit Theorem:

When sampling from almost any distribution,
 \bar{X} is approximately **Normally distributed** in **large samples**.

Show Sampling Distribution Simulation Applet:
file:///C:/Ivo.dir/UCLA_Classes/Winter2002/AdditionalInstructorAids/
[SamplingDistributionApplet.html](#)

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Central Limit Theorem – theoretical formulation

Let $\{X_1, X_2, \dots, X_k, \dots\}$ be a sequence of **independent** observations from **one specific random process**. Let and $E(X) = \mu$ and $SD(X) = \sigma$ and both be finite ($0 < \sigma < \infty; |\mu| < \infty$). If $\bar{X} = \frac{1}{n} \sum_{k=1}^n X_k$ **sample-avg**,

Then \bar{X} has a **distribution** which approaches $N(\mu, \sigma^2/n)$, as $n \rightarrow \infty$.

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Review

- What does the **central limit theorem** say? Why is it useful? (If the sample sizes are large, the **mean** in Normally distributed, as a RV)
- In what way might you expect the **central limit effect to differ** between **samples from a symmetric distribution** and **samples from a very skewed distribution**? (Larger samples for non-symmetric distributions to see CLT effects)
- What other important factor, apart from **skewness**, **slows down the action** of the **central limit effect**?

(Heavyness in the tails of the original distribution.)

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Review

- When you have data from a moderate to small sample and want to use a **normal approximation** to the distribution of \bar{X} in a calculation, what would you want to do before having any faith in the results? (30 or more for the sample-size, depending on the skewness of the distribution of X . Plot the data - non-symmetry and heavyness in the tails slows down the CLT effects).
- Take-home message: **CLT is an application of statistics of paramount importance**. Often, we are **not** sure of the distribution of an observable process. However, the CLT gives us a theoretical description of the **distribution of the sample means as the sample-size increases** ($N(\mu, \sigma^2/n)$).

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The standard error of the mean – remember ...

- For the sample mean calculated from a random sample, $SD(\bar{X}) = \frac{\sigma}{\sqrt{n}}$. This implies that the variability from sample to sample in the *sample-means* is given by the variability of the individual observations divided by the square root of the sample-size. In a way, *averaging decreases variability*.
- Recall that for *known* $SD(X)=\sigma$, we can express the $SD(\bar{X}) = \frac{\sigma}{\sqrt{n}}$. How about if $SD(X)$ is *unknown*!?

The standard error of the mean

The **standard error** of the sample mean is an estimate of the *SD* of the sample mean

- i.e. a measure of the precision of the **sample mean** as an estimate of the **population mean**
- given by $SE(\bar{x}) = \frac{\text{Sample standard deviation}}{\sqrt{\text{Sample size}}}$

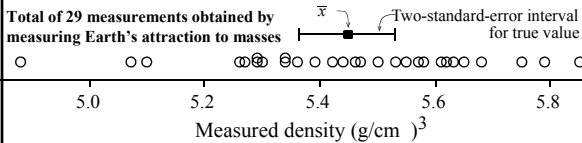
$$SE(\bar{x}) = \frac{s_x}{\sqrt{n}}$$

- Note similarity with
- $SD(\bar{X}) = \frac{\sigma}{\sqrt{n}}$.

Cavendish's 1798 data on mean density of the Earth, g/cm³, relative to that of H₂O

5.50	5.61	4.88	5.07	5.26	5.55	5.36	5.29	5.58	5.65
5.57	5.53	5.62	5.29	5.44	5.34	5.79	5.10	5.27	5.39
5.42	5.47	5.63	5.34	5.46	5.30	5.75	5.68	5.85	

Source: Cavendish [1798].



Newton's law of gravitation: $F = G \frac{m_1 m_2}{r^2}$, the attraction force F is the ratio of the product (Gravitational const, mass of body1, mass body2) and the distance between them, r . **Goal is to estimate G !**

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5.57	5.53	5.62	5.29	5.44	5.34	5.79	5.10	5.27	5.39
5.42	5.47	5.63	5.34	5.46	5.30	5.75	5.68	5.85	

Source: Cavendish [1798].

Sample mean $\bar{x} = 5.447931 \text{ g/cm}^3$

and sample SD = $s_x = 0.2209457 \text{ g/cm}^3$

Then the standard error for these data is:

$$SE(\bar{X}) = \frac{s_x}{\sqrt{n}} = \frac{0.2209457}{\sqrt{29}} = 0.04102858$$