Advanced Modeling and Inference Lecture Notes

# Chapter 1 Incomplete Data and the EM Algorithm

Qing Zhou<sup>\*,†</sup>

# Contents

1	Assu	mptions
	1.1	Ignorability
	1.2	Observed data likelihood and posterior
2	The	EM algorithm and its properties
	2.1	The algorithm
	2.2	EM as MM Algorithm 5
	2.3	Properties of the EM
	2.4	Missing information and convergence rate
	2.5	Another example
3	$\mathbf{E}\mathbf{M}$	for exponential families
	3.1	Exponential families
	3.2	MLE for complete data
	3.3	EM for incomplete data 10
4	Inco	mplete normal data 12
	4.1	The complete-data model $\ldots \ldots 12$
	4.2	Sufficient statistics and conditional distributions
	4.3	EM algorithm for incomplete normal data
5	Prob	olem set
Re	feren	ces

## 1. Assumptions

Reading: Schafer (1997), Section 2.1 to 2.3. Let Y be an  $n \times p$  matrix of complete data,  $Y = (Y_{obs}, Y_{mis})$ ,  $y_i$  be the  $i^{th}$  row of Y, i = 1, ..., n.

Variables	1	2	 p
1			
2		?	?
n	?	?	

Example of missing data

\*UCLA Department of Statistics (email: zhou@stat.ucla.edu).

 $<sup>^{\</sup>dagger}\mathrm{I}$  thank Elvis Cui for type setting part of this chapter in LaTex.

Under the iid assumption, the probability density of Y

$$p(Y \mid \theta) = \prod_{i=1}^{n} f(y_i \mid \theta),$$

where  $\theta$  is the parameter for this data generation model.

#### 1.1. Ignorability

<u>Missing at random</u> (MAR) is defined in terms of a probability model for the missingness. Let  $R = (r_{ij})$  be an  $n \times p$  matrix of indicator variables:  $r_{ij} = 1$  if  $y_{ij}$  is observed and  $r_{ij} = 0$  otherwise. We put a probability model for R,  $p(R \mid Y, \xi)$ , where  $\xi$  is some parameter. The MAR assumption is that

$$p(R \mid Y_{\text{obs}}, Y_{\text{mis}}, \xi) = p(R \mid Y_{\text{obs}}, \xi), \tag{1}$$

that is,  $R \perp Y_{\text{mis}} \mid Y_{\text{obs}}$ . A stronger assumption is missing completely at random (MCAR):  $R \perp (Y_{\text{mis}}, Y_{\text{obs}})$ . If neither holds, then the data are missing not at random (MNAR): R depends on  $Y_{\text{mis}}$ .

Consider an example in Mohan and Pearl (2021): A study in a school measured age (A), gender (G), and obesity (O) for students, with missing values in O since some students fail to reveal weight.

- MCAR: some students accidentally lost questionnaires  $(R \perp A, G, O)$ .
- MAR: some teenagers not reporting weight  $(R \perp O \mid A)$ .
- MNAR: overweight students reluctant to report weight  $(O \rightarrow R)$ .

Distinctness of parameters. Let  $\theta$  denote the parameters of the data model, and  $\xi$  the parameters of the missingness mechanism. Then,  $\theta$  and  $\xi$  are distinct if (a) **Bayesian**: any joint prior on  $(\theta, \xi)$  must factor into independent marginal priors for  $\theta$  and  $\xi$ , that is:

$$\pi(\theta,\xi) = \pi_{\theta}(\theta)\pi_{\xi}(\xi).$$

(b) **Frequentist**: joint parameter space of  $(\theta, \xi)$  is the Cartesian product of the individual parameter spaces for  $\theta \in \Theta$  and  $\xi \in \Gamma$ . That is:

$$(\theta, \xi) \in \Theta \times \Gamma.$$

MAR & distinctness  $\Rightarrow$  the missing-data mechanism is **ignorable**.

## 1.2. Observed data likelihood and posterior

$$\begin{split} \mathbb{P}(R, Y_{obs} | \theta, \xi) &= \int_{\Omega_{miss}} \mathbb{P}(R, Y | \theta, \xi) dY_{miss} \\ &= \int \mathbb{P}(R | Y, \theta, \xi) \mathbb{P}(Y | \theta, \xi) dY_{miss} \\ &= \int \mathbb{P}(R | Y, \xi) \mathbb{P}(Y | \theta) dY_{miss} \\ &= \mathbb{P}(R | Y_{obs}, \xi) \int \mathbb{P}(Y | \theta) dY_{miss} \quad \text{by MAR} \\ &= \mathbb{P}(R | Y_{obs}, \xi) \mathbb{P}(Y_{obs} | \theta). \end{split}$$

Consider the maximum likelihood estimate (MLE) of  $(\theta, \xi)$ . Under distinctness,

$$\max_{(\theta,\xi)\in\Theta\times\Gamma} \mathbb{P}(R,Y_{obs}|\theta,\xi) = \left\{ \max_{\xi\in\Gamma} \mathbb{P}(R|Y_{obs},\xi) \right\} \left\{ \max_{\theta\in\Theta} \mathbb{P}(Y_{obs}|\theta) \right\}$$

is separable. Define the observed-data likelihood  $L(\theta|Y_{obs}) := \mathbb{P}(Y_{obs}|\theta)$ . If both MAR and distinctness hold, we have the following MLE of  $\theta$ :

$$\widehat{\theta}_{\text{MLE}} = \operatorname*{argmax}_{\theta \in \Theta} \mathbb{P}(Y_{obs} | \theta) = \operatorname*{argmax}_{\theta \in \Theta} L(\theta | Y_{obs}).$$

Now for the *posterior* distribution of the parameters:

$$\begin{split} \mathbb{P}(\theta,\xi|Y_{obs},R) &\propto \mathbb{P}(R,Y_{obs}|\theta,\xi)\pi(\theta,\xi) \\ &=^{\mathrm{MAR}} \mathbb{P}(R|Y_{obs},\xi)\mathbb{P}(Y_{obs}|\theta)\pi(\theta,\xi) \\ &=^{\mathrm{Distinctness}} \mathbb{P}(R|Y_{obs},\xi)\mathbb{P}(Y_{obs}|\theta)\pi_{\theta}(\theta)\pi_{\xi}(\xi). \end{split}$$

Then we could derive the posterior of  $\theta$ :

$$\mathbb{P}(\theta|Y_{obs}, R) = \int \mathbb{P}(\theta, \xi|Y_{obs}, R)d\xi$$
$$\propto \mathbb{P}(Y_{obs}|\theta)\pi_{\theta}(\theta) \int h(R, Y_{obs}, \xi)d\xi$$
$$\propto L(\theta|Y_{obs})\pi_{\theta}(\theta),$$

where  $h(R, Y_{obs}, \xi)$  is a function independent of  $\theta$  and  $L(\theta|Y_{obs})$  is the observed data likelihood. Therefore, the observed-data posterior:

$$\mathbb{P}(\theta|Y_{obs}, R) = \mathbb{P}(\theta|Y_{obs}) \propto \mathbb{P}(Y_{obs}|\theta)\pi_{\theta}(\theta).$$

## 2. The EM algorithm and its properties

Reading: Schafer (1997), Section 3.2 and 3.3. Also see Dempster, Laird and Rubin (1977) and Wu (1983).

$$\widehat{\theta}_{\mathrm{MLE}} = \operatorname*{argmax}_{\theta \in \Theta} \mathbb{P}(Y_{\mathrm{obs}} | \theta) = \operatorname*{argmax}_{\theta \in \Theta} \int \mathbb{P}(Y_{\mathrm{obs}}, Y_{\mathrm{miss}} | \theta) dY_{\mathrm{miss}}.$$

#### 2.1. The algorithm

**Definition 1** (EM Algorithm). First, start with an initial  $\theta^{(0)}$ . For the  $(t+1)^{th}$  iteration:

• E-step: Calculate the expectation of complete-data log-likelihood:

$$Q(\theta|\theta^{(t)}) := \mathbb{E}[\log \mathbb{P}(Y_{obs}, Y_{miss}|\theta)|Y_{obs}, \theta^{(t)}].$$

• M-step: Find  $\theta^{(t+1)}$  by maximizing  $Q(\theta|\theta^{(t)})$ :

$$\theta^{(t+1)} := \operatorname*{argmax}_{\theta \in \Theta} Q(\theta | \theta^{(t)}).$$

Iterate the above 2 steps until convergence.

**Remark 1.** The expectation in the E-step is taken with respect to  $\mathbb{P}(Y_{miss}|Y_{obs}, \theta^{(t)})$  (conditional distribution), but not  $\mathbb{P}(Y_{miss}|\theta^{(t)})$  (marginal distribution).

**Example 1** (Bivariate binary data).  $Y_1$  and  $Y_2$  are correlated binary variables on  $\{1, 2\}$ . Missing values occur on either  $Y_1$  or  $Y_2$  in an i.i.d. sample of n units. We want to estimate  $\theta = (\theta_{11}, \theta_{12}, \theta_{21}, \theta_{22})$ , where  $\theta_{ij} := \mathbb{P}(Y_1 = i, Y_2 = j)$ . Complete data:  $X = (x_{11}, x_{12}, x_{21}, x_{22})$  (2 × 2 contingency table), where  $x_{ij}$  is the number of units with  $Y_1 = i$  and  $Y_2 = j$ . Complete data log-likelihood:

$$\ell(\theta|X) = \sum_{i,j=1}^{2} x_{ij} \log \theta_{ij}.$$

According to the missingness pattern, we partition the n units into three blocks:

-

A: Both observed					
$Y_1 \backslash Y_2$	1	2			
1	$x_{11}^A$	$x_{12}^{A}$	$\begin{vmatrix} x_{1+}^A \end{vmatrix}$		
2	$x_{21}^A$	$x_{22}^{A}$	$ x_{2+}^{A} $		
	$x_{\pm 1}^A$	$x_{\pm 2}^A$			

B: .	$r_2$ m	nssi	ng
$Y_1 \backslash Y_2$	1	2	
1			$x_{1+}^{B}$
2			$r^B$

C: $Y_1$ missing					
$Y_1 \backslash Y_2$	1	2			
1					
2					
	$x_{+1}^{C}$	$x_{\pm 2}^C$			

Then we have:

$$(x_{i1}^B, x_{i2}^B)|Y_{obs}, \theta^{(t)} \sim \mathcal{M}\left(x_{i+}^B, \left(\frac{\theta_{i1}^{(t)}}{\theta_{i+}^{(t)}}, \frac{\theta_{i2}^{(t)}}{\theta_{i+}^{(t)}}\right)\right), \quad i = 1, 2.$$

$$(x_{1j}^C, x_{2j}^C)|Y_{obs}, \theta^{(t)} \sim \mathcal{M}\left(x_{+j}^C, \left(\frac{\theta_{1j}^{(t)}}{\theta_{+j}^{(t)}}, \frac{\theta_{2j}^{(t)}}{\theta_{+j}^{(t)}}\right)\right), \qquad j = 1, 2.$$

where  $\theta_{i+}^{(t)} = \theta_{i1}^{(t)} + \theta_{i2}^{(t)}$ ,  $\theta_{+j}^{(t)} = \theta_{1j}^{(t)} + \theta_{2j}^{(t)}$ . Thus we derive the EM algorithm as follows:

• E-step: To calculate  $\mathbb{E}[\ell(\theta|X)|Y_{obs}, \theta^{(t)}]$ , let

$$x_{ij}^{(t)} := \mathbb{E}(x_{ij}|Y_{obs}, \theta^{(t)}) = x_{ij}^A + x_{i+}^B \frac{\theta_{ij}^{(t)}}{\theta_{i+}^{(t)}} + x_{+j}^C \frac{\theta_{ij}^{(t)}}{\theta_{+j}^{(t)}}, \quad 1 \le i, j \le 2.$$

Then

$$Q(\theta \mid \theta^{(t)}) = \mathbb{E}[\ell(\theta | X) | Y_{obs}, \theta^{(t)}] = \sum_{i,j} x_{ij}^{(t)} \log \theta_{ij}.$$

• M-step: Maximizing  $Q(\theta \mid \theta^{(t)})$  subject to  $\sum_{i,j} \theta_{ij} = 1$ , we have

$$\theta_{ij}^{(t+1)} = \frac{x_{ij}^{(t)}}{n} = \frac{1}{n} \left[ x_{ij}^A + x_{i+}^B \frac{\theta_{ij}^{(t)}}{\theta_{i+}^{(t)}} + x_{+j}^C \frac{\theta_{ij}^{(t)}}{\theta_{+j}^{(t)}} \right].$$

## 2.2. EM as MM Algorithm

**MM Algorithm**: Minorization-Maximization Algorithm. It was first proposed by Professor Jan de Leeuw at UCLA. We start with a simple identity:

$$\log \mathbb{P}(Y_{miss}, Y_{obs} | \theta) = \ell(\theta | Y_{obs}) + \log \mathbb{P}(Y_{miss} | Y_{obs}, \theta).$$

Now denote by F any distribution for  $Y_{miss}.$  Then re-arrange the above equation to get

$$\ell(\theta|Y_{obs}) = \log \mathbb{P}(Y_{miss}, Y_{obs}|\theta) - \log F(Y_{miss}) + \log \frac{F(Y_{miss})}{\mathbb{P}(Y_{miss}|Y_{obs}, \theta)}.$$

Take expectation on both sides w.r.t. F (L.H.S. is a constant since it does not involve  $Y_{miss}$ ):

$$\ell(\theta|Y_{obs}) = \mathbb{E}_F[\log \mathbb{P}(Y_{miss}, Y_{obs}|\theta)] + H(F) + D(F||\mathbb{P}(Y_{miss}|Y_{obs}, \theta)),$$

where H(F) denotes the entropy of distribution F and  $D(\cdot \| \cdot)$  denotes the Kullback-Leibler divergence. Since  $D(\cdot \| \cdot) \ge 0$ , thus for any F we have:

$$\ell(\theta|Y_{obs}) \ge \mathbb{E}_F[\log \mathbb{P}(Y_{miss}, Y_{obs}|\theta)] + H(F) := L(\theta, F),$$

and equality holds when  $F = \mathbb{P}(Y_{miss}|Y_{obs}, \theta)$ . Let  $F^{(t)} = \mathbb{P}(Y_{miss}|Y_{obs}, \theta^{(t)})$ . Then  $L(\theta, F^{(t)})$ , called a minorization function of  $\ell(\theta|Y_{obs})$ , satisfies the following two conditions:

(i) 
$$\ell(\theta|Y_{obs}) \ge L(\theta, F^{(t)})$$
 for any  $\theta$ ;  
(ii)  $\ell(\theta^{(t)}|Y_{obs}) = L(\theta^{(t)}, F^{(t)})$ .

EM iterates between two steps:

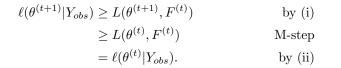
1. Minorization (E-step): Find  $L(\theta, F^{(t)})$  by calculating

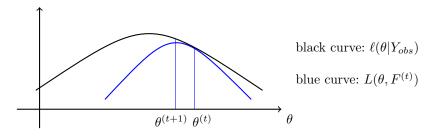
$$\mathbb{E}_{F^{(t)}}[\log \mathbb{P}(Y_{miss}, Y_{obs}|\theta)] = Q(\theta|\theta^{(t)}).$$

Note that  $L(\theta, F^{(t)}) = Q(\theta|\theta^{(t)}) + H(F^{(t)})$ , where  $H(F^{(t)})$  is a constant w.r.t  $\theta$  and thus can be omitted.

2. Maximization (M-step):  $\max_{\theta} L(\theta, F^{(t)}) \Leftrightarrow \max_{\theta} Q(\theta|\theta^{(t)})$  to obtain  $\theta^{(t+1)}$ .

Then, we can show the ascent property (Proposition 1) of the EM:





2.3. Properties of the EM

To establish the ascent property of the EM algorithm, we need the following inequality:

**Lemma 1** (Jensen's inequality). Assume that a random variable W is defined in the interval (a, b). If h(W) is convex on (a, b), then

$$\mathbb{E}[h(W)] \ge h[\mathbb{E}(W)],$$

provided that both expectations exist. For a strictly convex function, equality hold iff  $W = \mathbb{E}(W)$  a.s.

*Proof.* Use the supporting hyperplane theorem. Denote g(W) as the supporting hyperplane of h(W) at point  $w_0 = \mathbb{E}(W)$ . By convexity, we have  $h(w) \ge g(w) \ \forall w \in (a, b)$ , and thus,

$$\mathbb{E}[h(W)] \ge \mathbb{E}[g(W)] = g[\mathbb{E}(W)] = h[\mathbb{E}(W)].$$

The second equality is due to the linearity of  $\mathbb{E}(\cdot)$  and  $g(\cdot)$ .

**Proposition 1** (Ascent property of the EM). Let  $\ell(\theta|Y_{obs}) := \log \mathbb{P}(Y_{obs}|\theta)$ , which is the observed-data log-likelihood. Then the EM iterations satisfy

$$\ell(\theta^{(t+1)}|Y_{obs}) \ge \ell(\theta^{(t)}|Y_{obs}).$$

Proof. There are three crucial steps. First, write

$$\ell(\theta|Y_{obs}) = \log \mathbb{P}(Y_{obs}|\theta) = Q(\theta|\theta^{(t)}) - H(\theta|\theta^{(t)}),$$

where

$$H(\theta|\theta^{(t)}) = \int \left[\log \mathbb{P}(Y_{miss}|Y_{obs},\theta)\right] \mathbb{P}(Y_{miss}|Y_{obs},\theta^{(t)}) dY_{mis}.$$

Note that  $-H(\theta^{(t)}|\theta^{(t)})$  is the entropy of the distribution  $[Y_{miss}|Y_{obs}, \theta^{(t)}]$ . Second, we have

$$Q(\theta^{(t)}|\theta^{(t)}) \le Q(\theta^{(t+1)}|\theta^{(t)})$$

since  $\theta^{(t+1)}$  is a maximizer of  $Q(\bullet|\theta^{(t)})$ . Third, note that by Jensen's inequality and convexity of  $-\log(\cdot)$ :

$$H(\theta^{(t)}|\theta^{(t)}) - H(\theta^{(t+1)}|\theta^{(t)}) = \mathbb{E}\left\{\log\frac{\mathbb{P}(Y_{miss}|Y_{obs},\theta^{(t)})}{\mathbb{P}(Y_{miss}|Y_{obs},\theta^{(t+1)})}\right| Y_{obs},\theta^{(t)}\right\} \ge 0.$$

Therefore,

$$\ell(\theta^{(t)}|Y_{obs}) = Q(\theta^{(t)}|\theta^{(t)}) - H(\theta^{(t)}|\theta^{(t)})$$
  

$$\leq Q(\theta^{(t+1)}|\theta^{(t)}) - H(\theta^{(t+1)}|\theta^{(t)}) = \ell(\theta^{(t+1)}|Y_{obs}).$$

**Theorem 1** (Convergence property of the EM). Under some conditions, the sequence  $\{\theta^{(t)}\}$  defined by the EM iterations converges to a stationary point of the observed-data log-likelihood  $\ell(\theta|Y_{obs})$ .

#### 2.4. Missing information and convergence rate

Recall that  $Q(\theta|\theta) = \ell(\theta|Y_{obs}) + H(\theta|\theta)$ . Taking second derivatives on both sides:

$$\underbrace{-\frac{\partial^2}{\partial \theta^2}Q(\theta|\theta)}_{\mathcal{I}_C(\theta)} = \underbrace{-\frac{\partial^2}{\partial \theta^2}\ell(\theta|Y_{obs})}_{\mathcal{I}_O(\theta)} + \underbrace{(-\frac{\partial^2}{\partial \theta^2}H(\theta|\theta))}_{\mathcal{I}_M(\theta)}$$

Thus,  $\mathcal{I}_C(\theta) = \mathcal{I}_O(\theta) + \mathcal{I}_M(\theta)$ . This is called **missing information principle**. For regular problems where  $\theta^{(t+1)} \leftarrow \frac{\partial Q(\theta|\theta^{(t)})}{\partial \theta} = 0$ , we have

$$(\theta^{(t+1)} - \widehat{\theta}) \doteq D(\theta^{(t)} - \widehat{\theta}),$$

when  $\theta^{(t)}$  is close to the MLE  $\hat{\theta} = \operatorname{argmax}_{\theta} \ell(\theta | Y_{obs})$ . Here,  $D = \mathcal{I}_C(\hat{\theta})^{-1} \mathcal{I}_M(\hat{\theta})$  is called the fraction of missing information. Therefore after r iterations,

$$(\theta^{(t+r)} - \widehat{\theta}) \doteq D^r (\theta^{(t)} - \widehat{\theta}),$$

which shows that the convergence rate of EM is governed by the largest eigenvalue of D.

#### 2.5. Another example

Example 2. Multinomial distribution with cell probabilities

$$(\pi_1, \pi_2, \pi_3, \pi_4) = \left(\frac{1}{2} + \frac{\theta}{4}, \frac{1-\theta}{4}, \frac{1-\theta}{4}, \frac{\theta}{4}\right),$$

where  $\theta \in (0, 1)$  is the only unknown parameter. Given observations

$$y = (y_1, y_2, y_3, y_4), \qquad \sum_{i=1}^4 y_i = n,$$

we want to find the MLE of  $\theta$ .

We could directly maximize the likelihood via numerical optimization, but we could also use EM algorithm, i.e., treat this as a missing data problem. Split the first category  $\pi_1 = \pi_{11} + \pi_{12}, \pi_{11} = \frac{1}{2}, \pi_{12} = \frac{\theta}{4}$ . Therefore, the complete data is  $y_{cmp} = (y_{11}, y_{12}, y_2, y_3, y_4)$ . The complete data log-likelihood is:

$$\ell(\theta|y_{cmp}) = y_{11}\log\frac{1}{2} + (y_{12} + y_4)\log\frac{\theta}{4} + (y_2 + y_3)\log\frac{1-\theta}{4}$$
$$= (y_{12} + y_4)\log\theta + (y_2 + y_3)\log(1-\theta) + \text{constant}.$$

EM algorithm:

• E-step: Calculate

$$\mathbb{E}(y_{12} \mid y, \theta^{(t)}) = y_1 \frac{\theta^{(t)}/4}{1/2 + \theta^{(t)}/4} := y_{12}^{(t)}.$$

Then

$$Q(\theta \mid \theta^{(t)}) = \mathbb{E}[\ell(\theta \mid y_{cmp}) \mid y, \theta^{(t)}] = (y_{12}^{(t)} + y_4) \log \theta + (y_2 + y_3) \log(1 - \theta) + \text{constant.}$$

• M-step: Maximizing  $Q(\theta \mid \theta^{(t)})$  (binomial log-likelihood),

$$\theta^{(t+1)} = \frac{y_{12}^{(t)} + y_4}{y_{12}^{(t)} + y_4 + y_2 + y_3}$$

# 3. EM for exponential families

## 3.1. Exponential families

**Definition 2.** A family of pdfs or pmfs is called an exponential family (EF) if it can be expressed as

$$f(x \mid \theta) = h(x)c(\theta) \exp\left[\phi(\theta)^{\mathsf{T}}t(x)\right], \qquad (2)$$

where  $\theta = (\theta_m)_{1:d} \in \mathbb{R}^d$ ,  $\phi(\theta) = (\phi_j(\theta))_{1:k} \in \mathbb{R}^k$ ,  $t(x) = (t_j(x))_{1:k} \in \mathbb{R}^k$  and  $d \leq k$ . If d < k, the family is called a curved exponential family.

**Theorem 2.** Suppose that  $f(x \mid \theta)$  and its partial derivatives  $\partial f(x \mid \theta) / \partial \theta_m$  are continuous in x and  $\theta$ . If X is a random variable with density  $f(x \mid \theta)$ , then

$$\mathbb{E}\left[\sum_{j=1}^{k} \frac{\partial \phi_j(\theta)}{\partial \theta_m} t_j(X)\right] = -\frac{\partial \log c(\theta)}{\partial \theta_m} \quad \text{for } m = 1, \dots, d.$$

**Theorem 3** (Sufficient statistic). Let  $Y_1, \ldots, Y_n$  be an iid sample of size n from  $f(\cdot \mid \theta)$ . Then

$$T(Y_1, \dots, Y_n) = \left(\sum_{i=1}^n t_1(Y_i), \dots, \sum_{i=1}^n t_k(Y_i)\right) := \sum_{i=1}^n t(Y_i)$$

is a sufficient statistic for  $\theta$ .

*Proof.* Let  $Y = (Y_1, \ldots, Y_n)$  and  $y_i$  be the observed value of  $Y_i$ . Then

$$f(y \mid \theta) = f(y_1, \dots, y_n \mid \theta) = \left[\prod_{i=1}^n h(y_i)\right] [c(\theta)]^n \exp\left[\phi(\theta)^\mathsf{T} \sum_{i=1}^n t(y_i)\right].$$

Suppose  $\sum_{i=1}^{n} t(y_i) = t^*$ . The conditional distribution  $[Y \mid T(Y) = t^*, \theta]$  is given by

$$p(y \mid t^*, \theta) \propto f(y \mid \theta) \cdot I(T(y) = t^*)$$
  
= 
$$\prod_{i=1}^n h(y_i) \cdot I(T(y) = t^*) \cdot [c(\theta)]^n \exp \left[\phi(\theta)^\mathsf{T} t^*\right]$$
  
$$\propto \prod_{i=1}^n h(y_i) \cdot I(T(y) = t^*),$$

which is independent of  $\theta$ .

## 3.2. MLE for complete data

Let  $T_j(y) = \sum_{i=1}^n t_j(y_i), j = 1, \dots, k$ . The log-likelihood given complete data

$$\ell(\theta \mid y) = n \log c(\theta) + \phi(\theta)^{\mathsf{T}} \sum_{i=1}^{n} t(y_i)$$
$$= n \log c(\theta) + \sum_{j=1}^{k} \phi_j(\theta) T_j(y).$$
(3)

The MLE is given by the solution to

$$\frac{\partial \ell(\theta \mid y)}{\partial \theta_m} = n \frac{\partial \log c(\theta)}{\partial \theta_m} + \sum_{j=1}^k \frac{\partial \phi_j(\theta)}{\partial \theta_m} T_j(y) = 0, \quad m = 1, \dots, d.$$

From Theorem 2 and that  $Y_i \sim f(\cdot \mid \theta)$ , we have

$$n\frac{\partial \log c(\theta)}{\partial \theta_m} = -n\mathbb{E}\left[\sum_{j=1}^k \frac{\partial \phi_j(\theta)}{\partial \theta_m} t_j(Y_1)\right],$$

and therefore, the MLE is given by the solution to

$$\sum_{j=1}^{k} \frac{\partial \phi_j(\theta)}{\partial \theta_m} T_j(y) = n \sum_{j=1}^{k} \frac{\partial \phi_j(\theta)}{\partial \theta_m} \mathbb{E}\left[t_j(Y_1)\right], \quad m = 1, \dots, d.$$

Assume that d = k and the matrix

$$\frac{\partial \phi}{\partial \theta} = \left(\frac{\partial \phi_j(\theta)}{\partial \theta_m}\right)_{k \times k}$$

is invertible, where  $\partial \phi_j(\theta) / \partial \theta_m$  is the  $(m, j)^{\text{th}}$  element. Then the MLE  $\hat{\theta} = (\hat{\theta}_1, \dots, \hat{\theta}_k)$  is the solution to

$$\frac{\partial \phi}{\partial \theta} \begin{pmatrix} T_1(y) \\ \vdots \\ T_k(y) \end{pmatrix} = n \frac{\partial \phi}{\partial \theta} \begin{pmatrix} \mathbb{E}t_1(Y_1) \\ \vdots \\ \mathbb{E}t_k(Y_1) \end{pmatrix}$$
$$\iff T_j(y) = n \mathbb{E}_{\theta}[t_j(Y_1)], \quad j = 1, \dots, k.$$

That is,

$$\sum_{i=1}^n t_j(y_i) = n \mathbb{E}_{\theta}[t_j(Y_1)] = \mathbb{E}_{\theta}\left[\sum_{i=1}^n t_j(Y_i)\right], \quad j = 1, \dots, k.$$

Note that the left-hand side is the observed value of the sufficient statistic and the right-hand side the expectation which depends on  $\theta$ .

**Example 3.**  $\mathcal{N}(\mu, \sigma^2)$  and  $\operatorname{Bin}(n, p)$ .

# 3.3. EM for incomplete data

Let  $y_{\rm obs}$  be the observed data.

• E-step:

$$Q(\theta \mid \theta^{(t)}) = \mathbb{E}\left[\ell(\theta \mid Y) \mid y_{\text{obs}}, \theta^{(t)}\right]$$
  
=  $n \log c(\theta) + \sum_{j=1}^{k} \phi_j(\theta) \mathbb{E}\left[T_j(Y) \mid y_{\text{obs}}, \theta^{(t)}\right]$  (due to (3))  
=  $n \log c(\theta) + \sum_{j=1}^{k} \phi_j(\theta) \mathbb{E}\left[\sum_{i=1}^{n} t_j(Y_i) \mid y_{\text{obs}}, \theta^{(t)}\right].$ 

• M-step:  $\theta^{(t+1)}$  is the solution to

$$\mathbb{E}\left[\sum_{i=1}^{n} t_j(Y_i) \, \middle| \, y_{\text{obs}}, \theta^{(t)}\right] = n \mathbb{E}_{\theta}[t_j(Y_1)], \quad j = 1, \dots, k.$$

**Example 4.** Let  $y_1, \ldots, y_n$  be iid observations from  $\mathcal{N}(\mu, 1)$ , but only  $\operatorname{sgn}(y_i)$  are observed for  $i = 1, \ldots, k$ . Find the MLE of  $\mu$ .

Let  $\phi(\cdot)$  and  $\Phi(\cdot)$  be the pdf and cdf of  $\mathcal{N}(0,1)$ , respectively. Suppose that  $\operatorname{sgn}(y_i) = 1$  for  $i = 1, \ldots, k_1$  and  $\operatorname{sgn}(y_i) = -1$  for  $i = k_1 + 1, \ldots, k_1 + k_2 = k$ .

$$\underbrace{(\underbrace{+\dots+}_{k_1}\mid\underbrace{-\dots-}_{k_2}\mid y_{k+1},\dots,y_n)}_{k}$$

(1) <u>By EM</u>: Regard  $y_1, \ldots, y_k$  as missing. Sufficient statistic for  $\mu$  is  $T = \sum_{i=1}^{n} Y_i$ . In E-step, calculate  $\mathbb{E}(T \mid y_{\text{obs}}, \mu^{(t)}) = \sum_i \mathbb{E}(Y_i \mid y_{\text{obs}}, \mu^{(t)})$ .

- (a) For i > k,  $\mathbb{E}(Y_i \mid y_{\text{obs}}, \mu^{(t)}) = y_i$ .
- (b) For  $i = 1, ..., k_1$ ,

$$\mathbb{E}(Y_i \mid y_{\text{obs}}, \mu^{(t)}) = \mathbb{E}(Y_i \mid Y_i > 0, \mu^{(t)}) = \mu^{(t)} + \frac{\phi(\mu^{(t)})}{\Phi(\mu^{(t)})}.$$

(c) For  $i = k_1 + 1, \dots, k$ ,

$$\mathbb{E}(Y_i \mid y_{\text{obs}}, \mu^{(t)}) = \mathbb{E}(Y_i \mid Y_i < 0, \mu^{(t)}) = \mu^{(t)} - \frac{\phi(\mu^{(t)})}{1 - \Phi(\mu^{(t)})}$$

M-step: Solve  $\mathbb{E}(T \mid y_{obs}, \mu^{(t)}) = n\mu(=\mathbb{E}_{\mu}(T))$  to obtain

$$\mu^{(t+1)} = \frac{1}{n} \left[ \sum_{i>k} y_i + k\mu^{(t)} + \left( \frac{k_1}{\Phi(\mu^{(t)})} - \frac{k_2}{1 - \Phi(\mu^{(t)})} \right) \phi(\mu^{(t)}) \right].$$
(4)

(2) <u>Direct approach</u>: Since  $P(Y_i > 0) = \Phi(\mu)$  and  $P(Y_i < 0) = 1 - \Phi(\mu)$ ,

$$p(y_{\text{obs}} \mid \mu) \propto [\Phi(\mu)]^{k_1} [1 - \Phi(\mu)]^{k_2} \exp\left[-\frac{1}{2} \sum_{i>k} (y_i - \mu)^2\right].$$

Thus, observed data log-likelihood

$$\ell(\mu \mid y_{\text{obs}}) = k_1 \log \Phi(\mu) + k_2 \log[1 - \Phi(\mu)] - \frac{1}{2} \sum_{i > k} (\mu - y_i)^2.$$

Therefore, setting

$$\frac{\partial \ell(\mu \mid y_{\text{obs}})}{\partial \mu} = \frac{k_1 \phi(\mu)}{\Phi(\mu)} - \frac{k_2 \phi(\mu)}{1 - \Phi(\mu)} - (n - k)\mu + \sum_{i > k} y_i = 0$$

shows that MLE  $\hat{\mu}$  satisfies

$$\hat{\mu} = \frac{1}{n} \left[ \sum_{i > k} y_i + k\hat{\mu} + \left( \frac{k_1}{\Phi(\hat{\mu})} - \frac{k_2}{1 - \Phi(\hat{\mu})} \right) \phi(\hat{\mu}) \right].$$
(5)

Compare (4) and (5):  $\hat{\mu}$  is a fixed point of the EM iteration, i.e.,  $\mu^{(t+1)} = \hat{\mu}$  if  $\mu^{(t)} = \hat{\mu}$ .

# 4. Incomplete normal data

# 4.1. The complete-data model

Complete data:  $Y = (y_{ij})_{n \times p}, y_i = (y_{i1}, y_{i2}, \dots, y_{ip}) \in \mathbb{R}^p$ , and

$$y_i | \theta \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, \Sigma), \quad i = 1, \dots, n.$$

Put  $\theta = (\mu, \Sigma)$ . Complete-data likelihood is

$$L(\theta|Y) \propto |\Sigma|^{-n/2} \exp\left\{-\frac{1}{2}\sum_{i=1}^{n} (y_i - \mu)^{\mathsf{T}} \Sigma^{-1}(y_i - \mu)\right\}.$$

Let  $S := \sum_{i=1}^{n} (y_i - \bar{y}) (y_i - \bar{y})^{\mathsf{T}} \in \mathbb{R}^{p \times p}$ . The exponent

$$\sum_{i=1}^{n} (y_i - \mu)^{\mathsf{T}} \Sigma^{-1} (y_i - \mu) = \operatorname{tr} \left[ \sum_{i} (y_i - \mu)^{\mathsf{T}} \Sigma^{-1} (y_i - \mu) \right]$$
$$= \operatorname{tr} \left[ \sum_{i} \Sigma^{-1} (y_i - \mu) (y_i - \mu)^{\mathsf{T}} \right]$$
$$= \operatorname{tr} (\Sigma^{-1} S) + \operatorname{tr} [\Sigma^{-1} n (\bar{y} - \mu) (\bar{y} - \mu)^{\mathsf{T}} \Sigma^{-1} (\bar{y} - \mu).$$

Therefore,

$$\ell(\theta|Y) = -\frac{n}{2}\log|\Sigma| - \frac{1}{2}\operatorname{tr}[\Sigma^{-1}S] - \frac{1}{2}n(\bar{y}-\mu)^{\mathsf{T}}\Sigma^{-1}(\bar{y}-\mu).$$

This gives us the maximum likelihood estimate of  $\theta$ :

$$\widehat{\mu}_{\text{MLE}} = \overline{y}, \quad \widehat{\Sigma}_{\text{MLE}} = \frac{1}{n}S.$$

## 4.2. Sufficient statistics and conditional distributions

We start with the log-likelihood given complete data,

$$\ell(\theta|Y) = -\frac{n}{2}\log|\Sigma| - \frac{1}{2}\sum_{i=1}^{n} \left(\mu^{\mathsf{T}}\Sigma^{-1}\mu - 2\mu^{\mathsf{T}}\Sigma^{-1}y_{i} + y_{i}^{\mathsf{T}}\Sigma^{-1}y_{i}\right)$$
$$= -\frac{n}{2}\log|\Sigma| - \frac{n}{2}\mu^{\mathsf{T}}\Sigma^{-1}\mu + \mu^{\mathsf{T}}\Sigma^{-1}\sum_{i}y_{i} - \frac{1}{2}\sum_{i}y_{i}^{\mathsf{T}}\Sigma^{-1}y_{i}.$$

Using properties of trace,

$$\sum_{i} y_{i}^{\mathsf{T}} \Sigma^{-1} y_{i} = \sum_{i} \operatorname{tr} \left( y_{i}^{\mathsf{T}} \Sigma^{-1} y_{i} \right) = \sum_{i} \operatorname{tr} \left( \Sigma^{-1} y_{i} y_{i}^{\mathsf{T}} \right) = \operatorname{tr} \left( \Sigma^{-1} \sum_{i} y_{i} y_{i}^{\mathsf{T}} \right).$$

Letting

$$T_1 := \sum_{i=1}^n y_i = n\bar{y}, \qquad T_2 := \sum_{i=1}^n y_i y_i^{\mathsf{T}} = Y^{\mathsf{T}} Y,$$

we arrive at

$$\ell(\theta|Y) = -\frac{n}{2}\log|\Sigma| - \frac{n}{2}\mu^{\mathsf{T}}\Sigma^{-1}\mu + \mu^{\mathsf{T}}\Sigma^{-1}T_1 - \frac{1}{2}\operatorname{tr}(\Sigma^{-1}T_2)$$
(6)

Note that

$$\mu^{\mathsf{T}} \Sigma^{-1} T_1 = \langle \Sigma^{-1} \mu, T_1 \rangle,$$
  
tr( $\Sigma^{-1} T_2$ ) =  $\langle \operatorname{vec}(\Sigma^{-1}), \operatorname{vec}(T_2) \rangle$ 

Therefore, (i)  $\mathcal{N}(\mu, \Sigma)$  is an exponential family and (ii)  $(T_1, T_2)$  is a sufficient statistic for  $\theta = (\mu, \Sigma)$ . Also we have the following facts:

- $\mathbb{E}_{\theta}(T_1) = n\mu;$   $\mathbb{E}_{\theta}(T_2) = n(\Sigma + \mu\mu^{\mathsf{T}}).$

Now we can find the MLE by solving

$$\sum_{i=1}^{n} y_i = n\mu,$$
$$\sum_{i=1}^{n} y_i y_i^{\mathsf{T}} = n(\Sigma + \mu\mu^{\mathsf{T}}),$$

which leads to

$$\widehat{\mu}_{\text{MLE}} = \frac{1}{n} \sum_{i=1}^{n} y_i = \bar{y}, \qquad \widehat{\Sigma}_{\text{MLE}} = \frac{1}{n} \sum_{i=1}^{n} y_i y_i^{\mathsf{T}} - \bar{y} \bar{y}^{\mathsf{T}} = \frac{1}{n} S.$$
(7)

**Theorem 4** (Conditional distributions). Suppose  $\mathbf{x} = (\mathbf{x}_1, \mathbf{x}_2) \sim \mathcal{N}(\mu, \Sigma)$ , where  $\mu = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix}$ . Then

$$\mathbf{x}_1 | \mathbf{x}_2 \sim \mathcal{N}(\mu_{1|2}(\mathbf{x}_2), \Sigma_{1|2}),$$

where  $\mu_{1|2}(\mathbf{x}_2) := \mu_1 + \Sigma_{12} \Sigma_{22}^{-1}(\mathbf{x}_2 - \mu_2)$  and  $\Sigma_{1|2} := \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$ .

## 4.3. EM algorithm for incomplete normal data

Illustration of missing values						
Variables	1	2	3	4		p
$y_i$	$\checkmark$	$\checkmark$	$\checkmark$	?	?	?

Let O(i) index the observed data in  $i^{th}$  observation, and M(i) index the missing data in  $i^{th}$  observation. By Theorem 4,

$$y_{i,M(i)} \mid y_{i,O(i)} \sim \mathcal{N} \left( \mu_{M(i)|O(i)}(y_{i,O(i)}), \Sigma_{M(i)|O(i)} \right),$$

which will be used in the E-step.

• E-step:

$$\mathbb{E}[\ell(\theta|Y)|Y_{obs}, \theta^{(t)}] = \mu^{\mathsf{T}} \Sigma^{-1} \underbrace{\mathbb{E}(T_1|Y_{obs}, \theta^{(t)})}_{*} - \frac{1}{2} \operatorname{tr}[\Sigma^{-1} \underbrace{\mathbb{E}(T_2|Y_{obs}, \theta^{(t)})}_{\boxtimes}] \\ - \frac{n}{2} \log|\Sigma| - \frac{n}{2} \mu^{\mathsf{T}} \Sigma^{-1} \mu.$$
(8)

1)  $* = \sum_{i} \mathbb{E}(y_i | Y_{obs}, \theta^{(t)})$  and

$$\mathbb{E}(y_{ij}|Y_{obs},\theta^{(t)}) = \begin{cases} y_{ij} & \text{if } j \in O(i) \\ y_{ij}^* & \text{if } j \in M(i) \end{cases},$$

where  $y_{i,M(i)}^* := \mathbb{E}(y_{i,M(i)}|y_{i,O(i)}, \theta^{(t)}) = \mu_{M(i)|O(i)}^{(t)}(y_{i,O(i)}).$ 2)  $\boxtimes = \sum_i \mathbb{E}(y_i y_i^\mathsf{T}|Y_{obs}, \theta^{(t)}).$  Note that

$$\mathbb{E}(y_i y_i^{\mathsf{T}} | Y_{obs}, \theta^{(t)}) = [\mathbb{E}(y_{ij} y_{ik} | Y_{obs}, \theta^{(t)})]_{p \times p}.$$

We have

$$\mathbb{E}(y_{ij}y_{ik}|Y_{obs},\theta^{(t)}) = \begin{cases} y_{ij}y_{ik} & \text{if } j,k \in O(i) \\ y_{ij}y_{ik}^* & \text{if } j \in O(i),k \in M(i) \\ y_{ij}^*y_{ik} & \text{if } j \in M(i),k \in O(i) \\ \left( \sum_{M(i)|O(i)}^{(t)} \right)_{jk} + y_{ij}^*y_{ik}^* & \text{if } j,k \in M(i) \end{cases}$$

The last case, i.e.  $j, k \in M(i)$ , is due to

$$Cov(y_{ij}, y_{ik} | y_{i,O(i)}, \theta^{(t)}) = \mathbb{E}(y_{ij} y_{ik} | y_{i,O(i)}, \theta^{(t)}) - y_{ij}^* y_{ik}^*.$$

• M-step:

Let  $T_1^{(t)} := \mathbb{E}(T_1|Y_{obs}, \theta^{(t)}), T_2^{(t)} := \mathbb{E}(T_2|Y_{obs}, \theta^{(t)})$ . Max (8) over  $\theta = (\mu, \Sigma)$  or solve the following equations for  $(\mu, \Sigma)$ 

$$T_1^{(t)} = \mathbb{E}_{\theta}(T_1) = n\mu$$
  
 $T_2^{(t)} = \mathbb{E}_{\theta}(T_2) = n(\Sigma + \mu\mu^{\mathsf{T}})$ 

to update:

$$\mu^{(t+1)} = \frac{1}{n} T_1^{(t)}, \qquad \Sigma^{(t+1)} = \frac{1}{n} T_2^{(t)} - (\mu^{(t+1)}) (\mu^{(t+1)})^{\mathsf{T}}.$$

Compare to (7).

# 5. Problem set

- 1. (a) Let f(x) and g(x) be probability densities defined on  $\mathbb{R}^n$ . Suppose f(x) > 0 and g(x) > 0 for all x. Show that  $\mathbb{E}_f(\log f) \ge \mathbb{E}_f(\log g)$  using Jensen's inequality, where  $\mathbb{E}_f(h) = \int h(x) f(x) dx$ .
  - (b) The entropy of a probability distribution p(x) on  $\mathbb{R}^n$  is

$$H(p) := -\mathbb{E}_p(\log p) = -\int p(x)\log p(x)dx$$

Among all distributions with mean  $\mu = \int xp(x)dx$  and covariance matrix  $\Sigma = \int (x - \mu)(x - \mu)^{\mathsf{T}}p(x)dx$ , prove that the multivariate normal distribution has the maximum entropy.

Hint: In fact, (b) is a special case of a more general result: Consider the Boltzmann distribution

$$p_{\beta}(x) \propto \exp[-\beta h(x)]$$

with energy function h(x) at inverse temperature  $\beta > 0$ . Define the average energy of a distribution q(x) by  $\mathbb{E}_q(h) = \int h(x)q(x)dx$ . Let  $U(\beta)$  be the average energy of  $p_\beta$ . Then among all distributions with average energy  $U(\beta)$ , the Boltzmann distribution  $p_\beta$  has the maximum entropy.

*Proof outline*: First show that the cross-entropy  $-\mathbb{E}_q(\log p_\beta)$  is a constant depending on  $\beta$  for any q with average energy  $U(\beta)$ . Then apply (a).

- 2. In a genetic linkage experiment, 197 animals are randomly assigned to four categories according to the multinomial distribution with cell probabilities  $\pi_1 = \frac{1}{2} + \frac{\theta}{4}$ ,  $\pi_2 = \frac{1-\theta}{4}$ ,  $\pi_3 = \frac{1-\theta}{4}$ , and  $\pi_4 = \frac{\theta}{4}$ . The corresponding observations are  $y = (y_1, y_2, y_3, y_4) = (125, 18, 20, 34)$ .
  - (a) Derive and implement an EM algorithm to estimate  $\theta$ .
  - (b) Plot the observed data log-likelihood function  $\ell(\theta \mid y)$  for  $\theta \in (0, 1)$ . Compare the maximum of this function with your EM estimate.
- 3. Consider an i.i.d. sample drawn from a bivariate normal distribution with mean  $\mu = (\mu_1, \mu_2)$  and covariance matrix

$$\Sigma = \left(\begin{array}{cc} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{array}\right).$$

Suppose that the first k observations are missing their first component, the next m observations are missing their second component, and the last r observations are complete. Derive an EM algorithm for estimating the mean assuming that the covariance matrix  $\Sigma$  is known.

- 4. Prove the following propositions.
  - (a) If  $Y \sim \mathcal{N}(\mu, 1)$ , then  $\mathbb{E}(Y \mid Y > 0) = \mu + \phi(\mu)/\Phi(\mu)$ .
  - (b) Under the assumptions of Theorem 2, if X is a random variable with pdf in an exponential family, then

$$\mathbb{E}\left[\sum_{j=1}^{k} \frac{\partial \phi_j(\theta)}{\partial \theta_m} t_j(X)\right] = -\frac{\partial \log c(\theta)}{\partial \theta_m} \quad \text{for } m = 1, \dots, d.$$

Hint: Start from the equality  $\int f(x \mid \theta) dx = 1$  and differentiate both sides.

## References

- DEMPSTER, A. P., LAIRD, N. M. and RUBIN, D. B. (1977). Maximum likelihood estimation from incomplete data via the EM algorithm (with discussion). Journal of the Royal Statistical Society Series B **39** 1–38.
- MOHAN, K. and PEARL, J. (2021). Graphical models for processing missing data. *Journal of the American Statistical Association* **116** 1023–1037.
- SCHAFER, J. L. (1997). Analysis of Incomplete Multivariate Data, 1st ed. Chapman & Hall/CRC.
- Wu, C. F. J. (1983). On the convergence properties of the EM algorithm. Annals of Statistics 11 95–103.