

Mon, May 3, 2010.

1. Partial regression and partial residual plots.
2. Serial correlation.
3. Autocovariance function.
4. ACF.
5. Correlogram.
6. Properties of correlograms.

1) Partial regression and partial residual plots.

Partial regression or added variable plots are described on p166 of chapter 6. We can remove the effect of the other  $x$ 's by regressing  $y$  on all  $x$  except  $x_i$  to get residuals  $\delta^{\wedge}$ , and regressing  $x_i$  on all other  $x$  to get residuals  $\gamma^{\wedge}$ . An added variable plot shows  $x\text{axis}=\gamma^{\wedge}$  and  $y\text{axis}=\delta^{\wedge}$ . Look for nonlinearity and especially for outliers. The slope is  $\beta^{\wedge}_i$ .

Partial residual plots are described in the handout. A partial residual plot shows  $y\text{axis}=e+\beta^{\wedge}_i x_i$  and  $x\text{axis}=x_i$ .  $y\text{axis} = y$  minus predicted effect from other variables. The slope is  $\beta^{\wedge}_i$ . Look for outliers and especially for nonlinearity.

2) Serial correlation.

Often when data are recorded sequentially in time, the values are correlated with one another. See e.g. LA temperatures.

Some examples are presented on p309 in ch9.

3) Autocovariance function.

For any  $t$ s,  $Y_t$ , define

$$\gamma(t_1, t_2) = \text{cov}(Y_{t_1}, Y_{t_2}) = E \{ [Y_{t_1} - E(Y_{t_1})][Y_{t_2} - E(Y_{t_2})] \}.$$

If  $E(Y_{t_1}) = E(Y_{t_2}) = \mu$ , and this function

$\gamma(t_1, t_2)$  only depends on the difference in time  $t_2 - t_1$ , which we'll call the *lag*, and denote  $k$ .

i.e.  $\gamma_k = \text{cov}(Y_t, Y_{t+k})$ , which is the same, for any  $t$ .

4) Autocorrelation function, ACF.

$$\text{Define } \rho(t_1, t_2) = \text{cor}(Y_{t_1}, Y_{t_2}) = \gamma(t_1, t_2) / \sqrt{\{V(Y_{t_1}) V(Y_{t_2})\}}.$$

Often  $\rho(t_1, t_2)$  only depends on the lag  $k=t_2-t_1$ , and we write

$$\rho_k = \text{cor}(Y_t, Y_{t+k}), \text{ which is the same for any } t.$$

If  $E(Y_t) = \mu$  for all  $t$  and  $V(Y_t) = \sigma^2$  for all  $t$ , then  $\rho_k = \gamma_k / \sigma^2$  or

$$\rho_k = \gamma_k / \gamma_0.$$

$\rho_k$  is the auto-correlation function (acf).

## 5. Correlogram.

Note that both the autocovariance and autocorrelation are theoretical properties of a ts. They depend on the expected value, for instance. Given a sample of  $n$  observations of a ts, we might estimate the sample autocovariance or sample autocorrelation.

Sample autocov =  $c_k = 1/n \sum (Y_t - \bar{Y})(Y_{t+k} - \bar{Y})$ . The sum is from  $t=1$  to  $n-k$ .  $\bar{Y}$  means the sample mean of  $Y = (Y_1 + \dots + Y_n) / n$

Similarly, you can compute the sample autocorrelation function (sample acf) =  $r_k = c_k / c_0$ .

A correlogram is a plot of  $r_k$  versus the lag,  $k$ .

## 6. Properties of correlograms (and autocorrelation functions).

a) Even:  $\rho_k = \rho_{-k}$ , and  $r_k = r_{-k}$ .

b) Both are between  $-1$  and  $1$ ; i.e.  $\leq 1$  in absolute value.

c)  $\rho_0 = r_0 = 1$ .

d) If  $Y_t$  has a seasonal component with period  $\tau$  (e.g. one year),

then  $r_k$  and  $\rho_k$  also have seasonal components with period  $\tau$ .

Often the correlogram starts out high and gradually decays.

For iid errors with mean 0 and variance  $\sigma^2$ ,  $\rho_k = 0$ , for  $k \neq 0$ .

$r_k \sim -1/n$ , +/- about  $2 / \sqrt{n}$ , for  $k \neq 0$ .

So for confidence bounds, you can use  $-1/n \pm 1.96/\sqrt{n}$ . People often use instead  $0 \pm 2/\sqrt{n}$ .