

Ordinary kriging in terms of the covariance function

The model:

The model assumption is:

$$Z(s) = \mu + \delta(s)$$

where $\delta(s)$ is a zero mean stochastic term with variogram $2\gamma(\cdot)$.

The Kriging System

The predictor assumption is

$$\hat{Z}(s_0) = \sum_{i=1}^n w_i Z(s_i)$$

It is a weighted average of the sample values, and $\sum_{i=1}^n w_i = 1$ to ensure unbiasedness. The w_i 's are the weights that will be estimated.

Kriging minimizes the mean squared error of prediction

$$\min \sigma_e^2 = E[(Z(s_0) - \hat{Z}(s_0))^2]$$

or

$$\min \sigma_e^2 = E \left[\left(Z(s_0) - \sum_{i=1}^n w_i Z(s_i) \right)^2 \right]$$

For second order stationary process the last equation can be written as:

$$\sigma_e^2 = C(0) - 2 \sum_{i=1}^n w_i C(s_0, s_i) + \sum_{i=1}^n \sum_{j=1}^n w_i w_j C(s_i, s_j) \quad (1)$$

See next page for the proof:

Let's examine $(Z(s_0) - \sum_{i=1}^n w_i Z(s_i))^2$:

$$\begin{aligned} & \left(z(s_0) - \sum_{i=1}^n w_i z(s_i) + \mu - \mu \right)^2 = \\ & \left\{ [z(s_0) - \mu] - \sum_{i=1}^n w_i [z(s_i) - \mu] \right\}^2 = \\ & [z(s_0) - \mu]^2 - 2 \sum_{i=1}^n w_i [z(s_i) - \mu][z(s_0) - \mu] + \sum_{i=1}^n \sum_{j=1}^n w_i w_j [z(s_i) - \mu][z(s_j) - \mu]. \end{aligned}$$

If we take expectations on the last expression we have

$$E [z(s_0) - \mu]^2 - 2 \sum_{i=1}^n w_i E [z(s_i) - \mu][z(s_0) - \mu] + \sum_{i=1}^n \sum_{j=1}^n w_i w_j E [z(s_i) - \mu][z(s_j) - \mu]$$

The expectations above are the covariances:

$$C(0) - 2 \sum_{i=1}^n w_i C(s_0, s_i) + \sum_{i=1}^n \sum_{j=1}^n w_i w_j C(s_i, s_j)$$

Therefore kriging minimizes

$$\begin{aligned} \sigma_e^2 &= E[(Z(s_0) - \sum_{i=1}^n w_i Z(s_i))]^2 = \\ & C(0) - 2 \sum_{i=1}^n w_i C(s_0, s_i) + \sum_{i=1}^n \sum_{j=1}^n w_i w_j C(s_i, s_j) \\ & \text{subject to} \\ & \sum_{i=1}^n w_i = 1 \end{aligned}$$

The minimization is carried out over (w_1, w_2, \dots, w_n) , subject to the constraint $\sum_{i=1}^n w_i = 1$. Therefore the minimization problem can be written as:

$$\min C(0) - 2 \sum_{i=1}^n w_i C(s_0, s_i) + \sum_{i=1}^n \sum_{j=1}^n w_i w_j C(s_i, s_j) - 2\lambda \left(\sum_{i=1}^n w_i - 1 \right) \quad (2)$$

where λ is the Lagrange multiplier. After differentiating (2) with respect to w_1, w_2, \dots, w_n , and λ and set the derivatives equal to zero we find that

$$\begin{aligned} 2 \sum_{j=1}^n w_j C(s_i, s_j) - 2C(s_0, s_i) - 2\lambda &= 0, \quad i = 1, \dots, n \\ \sum_{j=1}^n w_j C(s_i, s_j) - C(s_0, s_i) - \lambda &= 0, \quad i = 1, \dots, n \end{aligned}$$

and

$$\sum_{i=1}^n w_i = 1$$

Using matrix notation the previous system of equations can be written as

$$\mathbf{CW} = \mathbf{c}$$

Therefore the weights w_1, w_2, \dots, w_n and the Lagrange multiplier λ can be obtained by

$$\mathbf{W} = \mathbf{C}^{-1}\mathbf{c}$$

where

$$\mathbf{W} = (w_1, w_2, \dots, w_n, -\lambda)$$

$$\mathbf{c} = (C(s_0, s_1), C(s_0, s_2), \dots, C(s_0, s_n), 1)'$$

$$\mathbf{C} = \begin{cases} C(s_i, s_j), & i = 1, 2, \dots, n, \quad j = 1, 2, \dots, n, \\ 1, & i = n + 1, \quad j = 1, \dots, n, \\ 1, & j = n + 1, \quad i = 1, \dots, n, \\ 0, & i = n + 1, \quad j = n + 1. \end{cases}$$

The variance of the error of prediction:

So far, we found the weights and therefore we can compute the predictor: $\hat{Z}(s_0) = \sum_{i=1}^n w_i Z(s_i)$. How about the variance of the error of prediction, namely σ_e^2 ?

We multiply

$$\sum_{j=1}^n w_j C(s_i, s_j) - C(s_0, s_i) - \lambda = 0, \quad i = 1, \dots, n$$

by w_i and we sum over all $i = 1, \dots, n$ to get:

$$\sum_{i=1}^n \sum_{j=1}^n w_i w_j C(s_i, s_j) - \sum_{i=1}^n w_i C(s_0, s_i) - \sum_{i=1}^n w_i \lambda = 0$$

Therefore,

$$\sum_{i=1}^n \sum_{j=1}^n w_i w_j C(s_i, s_j) = \sum_{i=1}^n w_i C(s_0, s_i) + \lambda$$

If we substitute this result into equation (1) we finally get:

$$\sigma_e^2 = C(0) - \sum_{i=1}^n w_i C(s_i, s_0) + \lambda \tag{3}$$

The kriging system in terms of covariance

$$\begin{pmatrix} C(s_1, s_1) & C(s_1, s_2) & C(s_1, s_3) & \dots & C(s_1, s_n) & 1 \\ C(s_2, s_1) & C(s_2, s_2) & C(s_2, s_3) & \dots & C(s_2, s_n) & 1 \\ \dots & \dots & \ddots & \dots & \dots & 1 \\ \vdots & \vdots & \vdots & \ddots & \dots & 1 \\ C(s_n, s_1) & C(s_n, s_2) & C(s_n, s_3) & \dots & C(s_n, s_n) & 1 \\ 1 & 1 & \dots & \dots & 1 & 0 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \\ \vdots \\ \vdots \\ w_n \\ -\lambda \end{pmatrix} = \begin{pmatrix} C(s_0, s_1) \\ C(s_0, s_2) \\ \vdots \\ \vdots \\ C(s_0, s_n) \\ 1 \end{pmatrix}$$

Again we observe that the matrix \mathbf{C} must be positive definite and this ensured by a choice of a model covariance function.

Ordinary kriging using the covariance function:

The same example as in the previous handout (ordinary kriging using variogram) is solved using the covariance function: $C(h) = 10e^{-\frac{h}{3.33}}$. Reminder: The corresponding semivariogram function was $\gamma(h) = 10(1 - e^{-\frac{h}{3.33}})$.

$$\mathbf{W} = \mathbf{C}^{-1}\mathbf{c} = \begin{pmatrix} 10 & 5.103 & 0.435 & 0.199 & 0.489 & 0.259 & 0.048 & 1 \\ 5.103 & 10 & 0.362 & 0.202 & 0.905 & 0.489 & 0.061 & 1 \\ 0.435 & 0.362 & 10 & 2.902 & 0.199 & 0.111 & 0.362 & 1 \\ 0.199 & 0.202 & 2.902 & 10 & 0.244 & 0.152 & 1.222 & 1 \\ 0.489 & 0.905 & 0.199 & 0.244 & 10 & 5.103 & 0.224 & 1 \\ 0.259 & 0.489 & 0.111 & 0.152 & 5.103 & 10 & 0.193 & 1 \\ 0.048 & 0.061 & 0.362 & 1.222 & 0.224 & 0.193 & 10 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 \end{pmatrix}^{-1} \begin{pmatrix} 2.612 \\ 3.382 \\ 0.889 \\ 0.579 \\ 1.333 \\ 0.682 \\ 0.176 \\ 1 \end{pmatrix}.$$

The answer is:

$$\mathbf{W} = \begin{pmatrix} 0.174 \\ 0.317 \\ 0.129 \\ 0.086 \\ 0.151 \\ 0.057 \\ 0.086 \\ -0.906 \end{pmatrix} = \begin{pmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \\ w_5 \\ w_6 \\ w_7 \\ -\lambda \end{pmatrix}.$$

We observe that the weights are same as before when we used the variogram, and therefore

$$\hat{z}(s_0) = \sum_{i=1}^n w_i z(s_i) = 0.174(477) + \dots + 0.086(783) = 592.59.$$

The Lagrange multiplier is now $\lambda = -0.907$. However the variance of the estimator is the same as before because:

$$\sigma_e^2 = C(0) - \sum_{i=1}^n w_i C(s_i - s_0) + \lambda = 8.96.$$

Short code for ordinary kriging in terms of covariance:

```
a <- read.table("kriging_1.txt", header=TRUE) #See next page.
b <- read.table("kriging_11.txt", header=TRUE) #See next page.

x <- as.matrix(cbind(a$x, a$y))

x1 <- rep(rep(0,8),8)          #Initialize
dist <- matrix(x1,nrow=8,ncol=8) #the distance matrix

for (i in 1:8){
  for (j in 1:8){
    dist[i,j]=((x[i,1]-x[j,1])^2+(x[i,2]-x[j,2])^2)^.5
  }
}

c0 <- 0
c1 <- 10
alpha <- 3.33

x1 <- rep(rep(0,8),8)          #Initialize
C <- matrix(x1,nrow=8,ncol=8) #the C matrix

for(i in 1:8){
  for (j in 1:8){
    C[i,j]=c1*exp(-dist[i,j]/alpha)
    if(i==j){C[i,j]=c0+c1}
    if(i==8){C[i,j]=1}
    if(j==8){C[i,j]=1}
    if(i==8 & j==8) {C[i,j]=0}
  }
}

c <- rep(0,8)                  #Initialize
                                #the c vector

for(j in 1:8){
  c[j]=c1*exp(-dist[8,j]/alpha)
  if(j == 8) {c[j]=1}
}

w <- solve(C) %*% c           #Obtain the weights and the Lagrange parameter

z_hat <- w[-8] %*% b$z         #Compute the estimate
var_z_hat <- c0+c1 - t(w) %*% c #Compute the variance of the estimate
```

File kriging_1.txt: All the coordinates (observed data points plus the point to be predicted).

```
x y
61 139
63 140
64 129
68 128
71 140
73 141
75 128
65 137
```

File kriging_11.txt: Observed data points and their coordinates.

```
x y z
61 139 477
63 140 696
64 129 227
68 128 646
71 140 606
73 141 791
75 128 783
```