

Ch:8 NONLINEAR REGRESSION

8.1 Why nonlinear models

1.(Comment) The world abounds in nonlinear models.

(i) Mathematical model = differential equation

(ii) diff. eqn. \Rightarrow nonlinear model

2.(Growth eq.) $\frac{df}{dt} = \lambda f$

Sol: $f(t) = \gamma e^{\lambda t}$ = nonlinear model

3.(Unified Field Theory of Statistics)

Stat = Linear reg. + Nonlinear reg.

4.(Non-standard applications)

Maximum likelihood estimation

Robust estimation

5.(Note) $f = \gamma e^{\lambda t}$

Is nonlinear because it is nonlinear in λ
and **not** because it is nonlinear in t .

6.(Least squares fitting) Minimize

$$Q(\gamma, \lambda) = \sum_{i=1}^n (y_i - \gamma e^{\lambda t_i})^2$$

8.2 An overview of PROC NLIN

Make a standard program immediately available.

Focus attention on aspects of the subject used in practice.

8.3 The nonlinear regression model

1.(Model) $y_i = f(x_i, \theta) + e_i \quad ; \quad i = 1, \dots, n$

$$x_i = (x_{i1}, \dots, x_{it}) \quad , \quad \theta = \begin{pmatrix} \theta_1 \\ \vdots \\ \theta_p \end{pmatrix} \in \Theta$$

2.(Ex) $y_i = \gamma e^{\lambda t_i} + e_i$

$$x_i = t_i \quad , \quad \theta = \begin{pmatrix} \gamma \\ \lambda \end{pmatrix} \quad , \quad \Theta : \gamma \geq 0, \lambda \leq 0$$

3.(Vector form) $y = f(\theta) + e$

$$f(\theta) = (f_i(\theta)) \quad , \quad f_i(\theta) = f(x_i, \theta)$$

4.(Linear case)

$$y = X\theta + e \quad , \quad f(\theta) = X\theta$$

8.4 Nonlinear least squares

1.(Def) $\hat{\theta}$ is a **least squares estimate** of θ iff $\theta = \hat{\theta}$ minimizes:

$$Q(\theta) = \sum_{i=1}^n (y_i - f(x_i, \theta))^2 \quad (1)$$

$$= \|y - f(\theta)\|^2, \quad \theta \in \Theta \quad (2)$$

2.(Observation space picture)

3.(Variable space picture)

4.(Normal equations) If $\hat{\theta}$ is an interior point of Θ , then $\theta = \hat{\theta}$ satisfies

$$\sum_{i=1}^n \frac{\partial f_i}{\partial \theta_j} (y_i - f_i(\theta)) = 0, \quad j = 1, \dots, p$$

Pf: Differentiate $Q(\theta)$ w.r.t. θ_j .

5.(Vector form) Let

$$\frac{df}{d\theta} = \left(\frac{\partial f_i}{\partial \theta_j} \right) = \text{Jacobian of } f(\theta)$$

The normal equations become

$$\frac{df^T}{d\theta}(y - f(\theta)) = 0$$

6.(Linear case) $f(\theta) = X\theta$, $\frac{df}{d\theta} = X$

The normal equations are

$$X^T(y - X\theta) = 0$$

8.5 The Gauss-Newton algorithm

The algorithm

1.(Why)

- (i) Works well (Bard, 1970)
- (ii) Natural interface to linear theory
- (iii) Basis for many other algorithms and most programs
- (iv) Many non-standard applications

1.(Idea)

(i) Project $y - f(\theta)$ on tangent plane

(ii) Replace θ by $\theta + \Delta\theta$ and repeat

3.(Associated linear least squares problem) Minimize w.r.t. $\Delta\theta$

$$Q_{\theta}(\Delta\theta) = \|y - f(\theta) - \frac{df}{d\theta}\Delta\theta\|^2$$

4. (Gauss-Newton algorithm) The solution to 3 is

$$\Delta\theta = \left(\frac{df^T}{d\theta} \frac{df}{d\theta} \right) \frac{df^T}{d\theta} (y - f(\theta))$$

Standard modifications

Partial step modification:

1. (Partial step th) If θ is an interior point of Θ and $\Delta\theta$ is defined and non-zero, then a small enough step in the direction of $\Delta\theta$ will reduce $Q(\theta)$.

Pf: Recall that if A is positive definite and $x \neq 0$, then $x^T A x > 0$.

$$\frac{dQ}{d\theta} = -2(y - f)^T \frac{df}{d\theta}$$

thus

$$\begin{aligned} \lim_{\alpha \rightarrow 0} \frac{Q(\theta + \alpha \Delta\theta) - Q(\theta)}{\alpha} &= \frac{dQ}{d\theta} \Delta\theta \\ &= -2(y - f(\theta))^T \frac{df}{d\theta} \left(\frac{df^T}{d\theta} \frac{df}{d\theta} \right)^{-1} \frac{df^T}{d\theta} (y - f(\theta)) > \\ &0 \end{aligned}$$

2. (Step halving) $\Delta\theta$, $\Delta\theta/2$, $\Delta\theta/4$, \dots

Other modifications:

1.(Constraints)

$$a_i \leq \theta_i \leq b_i \quad , \quad i = 1, \dots, p$$

2.(Weights)

$$\begin{aligned} Q_w(\theta) &= \sum w_i (y_i - f_i(\theta))^2 \\ &= \sum (\sqrt{w_i} y_i - \sqrt{w_i} f_i(\theta))^2 \end{aligned}$$

The Gauss-Newton algorithm becomes

$$\Delta\theta = \left(\frac{df^T}{d\theta} W \frac{df}{d\theta} \right)^{-1} \frac{df^T}{d\theta} W (y - f(\theta))$$

$$W = \begin{pmatrix} w_1 & \cdots & 0 \\ 0 & & w_n \end{pmatrix}$$

Using the computer

1.(Logistic growth model)

$$f(t, \theta) = M \frac{e^{\alpha + \beta t}}{1 + e^{\alpha + \beta t}}, \quad \theta = (\alpha, \beta, M)'$$

2.(Ex 8.1) U.S. population

$$\frac{\partial f}{\partial M} = \frac{e^{\alpha+\beta t}}{1+e^{\alpha+\beta t}} \frac{df}{f} = p$$

$$\frac{\partial f}{\partial \alpha} = f(1 - p)$$

$$\frac{\partial f}{\partial \beta} = f(1 - p)t$$

Initial values:

$$M = 300 = \text{asymptote guess}$$

Fitting at $t = 1, 20$ (Text)

$$\alpha = -4.6, \beta = 0.29$$

Log model:

$$\log y = \log f + e$$

This makes exponential growth plot linearly on t . The derivatives are easy.

$$\frac{\partial}{\partial \theta} \log f = \frac{\partial f}{\partial \theta} / f$$

Statistical properties

1.(Assumptions)

y_1, \dots, y_n independent

$E y_i = f_i(\theta)$ unbiased

$$\text{var}(\sqrt{w_i}y_i) = \sigma^2$$

There is no formal advantage to the assumption of normality.

2.(Weighted least squares) $\hat{\theta}$ minimizes

$$Q_w(\theta) = \sum w_i (y_i - f_i(\theta))^2$$

3.(Distribution)

$$\hat{\theta} \underset{\sim}{\sim} N \left(\theta, \sigma^2 \left(\frac{df^T}{d\theta} W \frac{df}{d\theta} \right)^{-1} \right)$$

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4. (Residual mean square) Let

$$\hat{\sigma}^2 = Q_w(\hat{\theta}) / (n - p) \approx \sigma^2$$

5. (Standard error estimates)

$$\text{cov } \hat{\theta} = \hat{\sigma}^2 \left(\frac{d\hat{f}^T}{d\theta} W \frac{d\hat{f}}{d\theta} \right)^{-1}$$

6. (Functions of parameters)

$$\text{var } g(\hat{\theta}) = \frac{dg}{d\theta} (\text{cov } \hat{\theta}) \frac{dg^T}{d\theta}$$

Motivation:

$$g(\hat{\theta}) \approx g(\theta) + \frac{dg}{d\theta} (\hat{\theta} - \theta)$$

$$\text{var } g(\hat{\theta}) \approx \text{var} \left(\frac{dg}{d\theta} \hat{\theta} \right) = \frac{dg}{d\theta} (\text{cov } \hat{\theta}) \frac{dg^T}{d\theta}$$

7.(Intervals and tests)

$$\frac{g(\hat{\theta}) - g(\theta)}{\widehat{\text{std}} g(\hat{\theta})} \underset{\circ}{\sim} t(n - p)$$

8.(Corr)

$$\frac{\hat{\theta}_i - \theta_i}{\widehat{\text{std}} \hat{\theta}_i} \underset{\circ}{\sim} t(n - p)$$

$$\widehat{\text{var}} \hat{\theta}_i = \hat{\sigma}^2 \left(\frac{d\hat{f}^T}{d\theta} W \frac{d\hat{f}}{d\theta} \right)_{ii}^{-1}$$

9.(Ex 8.2) Maize , Table 8.2

$$\log y = \log f(t, \theta) + e$$

$$f(t, \theta) = M \frac{e^{\alpha + \beta t}}{1 + e^{\alpha + \beta t}}, \quad \theta = (\alpha, \beta, M)'$$

The problem specification is as in Fig 8.17

9.(Ex 8.2 Cont) Note that

$$\beta = \hat{\beta} \pm t_0 \text{std } \hat{\beta} = 0.113 \pm .010 = \text{output}$$

To estimate $f(t, \theta)$ at $t = 204$:

$$\log f = \hat{\log f} \pm t_0 \text{std}(\hat{\log f}) = 2.906 \pm .1943$$

$$15.1 < f < 22.2$$

For: $g(\theta) = M\beta/4 = \text{max growth rate}$

$$\frac{dg}{d\theta} = (0, M/4, \beta/4)$$

$$\text{var } \hat{g} = \frac{d\hat{g}}{d\hat{\theta}} (\text{cov } \hat{\theta}) \frac{d\hat{g}^T}{d\hat{\theta}}$$

$$= \frac{1}{16} (\hat{M}, \hat{\beta}) \begin{pmatrix} \text{var}(\hat{\beta}) & \text{cov}(\hat{\beta}, \hat{M}) \\ \text{cov}(\hat{M}, \hat{\beta}) & \text{var}(\hat{M}) \end{pmatrix} \begin{pmatrix} \hat{M} \\ \hat{\beta} \end{pmatrix}$$

$$= 0.1035$$

Trick:

Add case: 1 .

Add code: Fig 8.24

9.(Ex 8.2 cont)

$$f_{n+1} = M\beta/4 = g$$

$$\hat{g} = \hat{y}_{n+1} = 3.389, \text{ std } \hat{g} = .3219$$

Note: $(\text{std } \hat{g})^2 = .1036 = \text{value above}$

Goodness of fit and other hypotheses

1.(Restricted model)

$$y = f(\theta) + e \quad , \quad \theta \in \Theta_0 \subset \Theta$$

$$\hat{\theta} = \text{restricted LS est} \quad , \quad q = \dim \Theta_0$$

2.(Approximate F)

$$\frac{n - p}{p - q} \cdot \frac{Q_w(\hat{\theta}) - Q_w(\hat{\theta})}{Q_w(\hat{\theta})} \underset{\circ}{\sim} F(p - q, n - p)$$

Conditions: Text, p276

3.(Other notation)

$$\frac{n - p}{p - q} \cdot \frac{\text{RSS}_0 - \text{RSS}}{\text{RSS}} \underset{\circ}{\sim} F(p - q, n - p)$$

4.(Determining dimension)

$$f = \alpha_1 e^{\lambda_1 t} + \alpha_2 e^{\lambda_2 t} \quad , \quad p = 4$$

The hypotheses $\lambda_2 = 0$ gives

$$f_0 = \alpha_1 e^{\lambda_1 t} + \alpha_2 \quad , \quad q = 3$$

The hypothesis $\alpha_2 = 0$ gives

$$f_0 = \alpha_1 e^{\lambda_1 t} \quad , \quad q = 2$$

Note also

$$f = M \frac{e^{\alpha + \beta t}}{1 + e^{\alpha + \beta t}} \quad , \quad p = 3$$

has the restricted form

$$f_0 = \gamma e^{\beta t} \quad , \quad q = 2$$

Pf: Let $M = \gamma e^{-\alpha}$. As $\alpha \rightarrow -\infty$

$$f = \frac{\gamma e^{\beta t}}{1 + e^{\alpha + \beta t}} \rightarrow \gamma e^{\beta t}$$

5.(Ex 8.3, p277) Sulfate data, $n=21$

$$y = \alpha_1 e^{\lambda_1 t} + \alpha_2 e^{\lambda_2 t} + e \quad , \quad \text{RSS} = 0.815$$

$$y = \alpha e^{\lambda t} + e \quad , \quad \text{RSS}_0 = 47.69$$

$$F = \frac{21 - 4}{4 - 2} \cdot \frac{47.69 - 0.815}{0.815} = 489^{***}$$

6.(Ex 8.4, p278) Maize data, $n = 14$. Let

$$f = M \frac{e^{\alpha + \beta t}}{1 + e^{\alpha + \beta t}} \quad , \quad p = 3$$

Test

$$f_0 = \gamma e^{\lambda t} \quad , \quad q = 2$$

Using a log-transform

$$\text{RSS} = .3860 \quad , \quad \text{Fig 8.3}$$

$$\text{RSS}_0 = 5.1016 \quad , \quad \text{Simple linear reg}$$

$$F = \frac{14 - 3}{3 - 2} \cdot \frac{5.1016 - .3860}{.3860} = 134.4^{***}$$

as suggested by the plot in Fig 8.22 (p273).