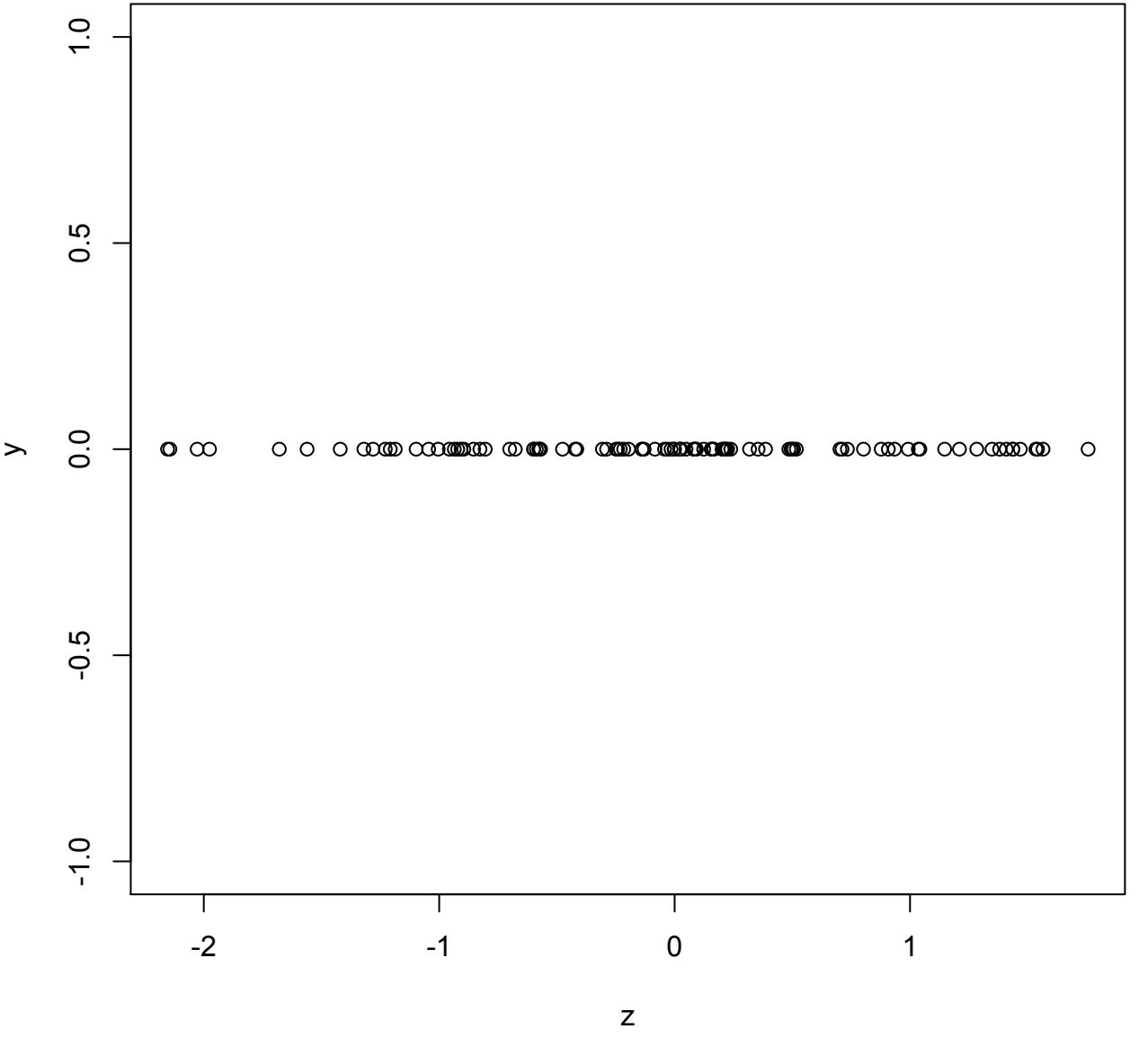
1.0
0.5
0.0
-0.5
-1.0
y
-2
-1
0
1
z