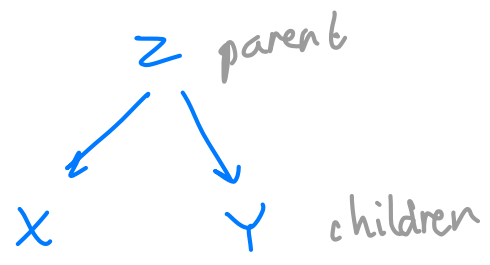


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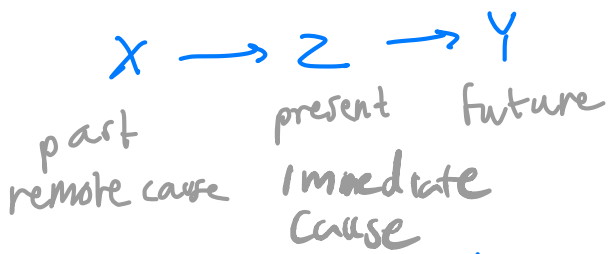
# Conditional Independence

$$X \perp Y | Z$$

(1) shared cause

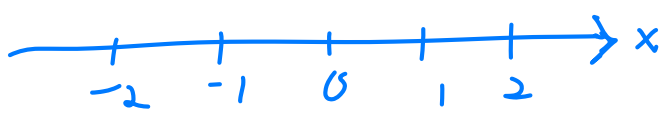


(2) Markovian



markov chain/random walk

$$X_0 \rightarrow X_1 \rightarrow X_2 \rightarrow \dots \rightarrow X_t \rightarrow X_{t+1} \rightarrow \dots$$



markovian property:

$$[X_{t+1} | X_t, X_{t-1}, \dots, X_0] \sim [X_{t+1} | X_t]$$

$$X_{t+1} = F(X_t, \Sigma_t)$$

$$\Sigma_t \perp (X_0, \dots, X_t)$$

$X_{t+1}$  only depends on previous step

joint density:

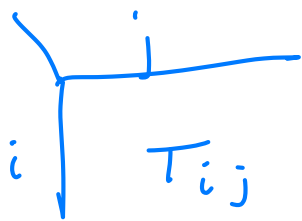
$$P(X_0, X_1, \dots, X_T) = p(x_0)p(x_1|x_0)p(x_2|x_1) \dots$$
$$= p(x_0) \prod_{t=1}^T p(x_t | x_{t-1}) \quad \text{notation 1}$$

Transition probability:

$$T(x, y) = P(X_{t+1} = y | X_t = x)$$

↓   ↓   ↓   ↓  
i   j   j   i

notation 2  
notation 3



## Recursive computation

notation 3

$$P_t(i) = P(X_t = i)$$

population migration interpretation

$P_t(i)$ : # of people @ state  $i$  @ time  $t$

$T_{ij}$ : fraction of people in state  $i$  who will go to state  $j$

notation 1

$$P(X_{t+1}) = \sum_{x_t} P(x_t, X_{t+1}) \rightarrow \text{marginalization}$$

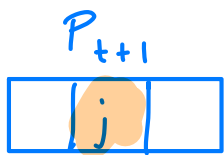
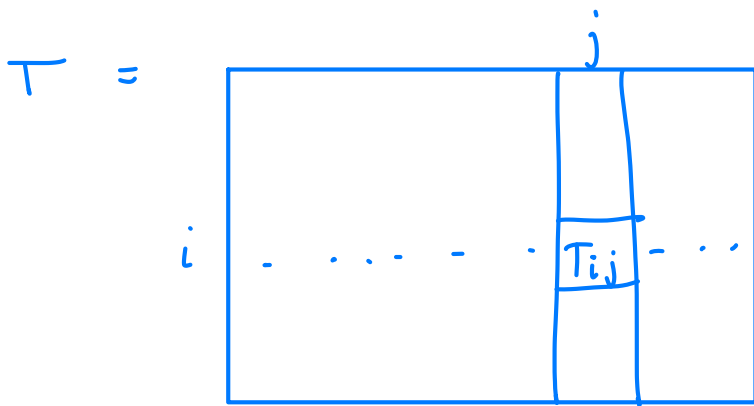
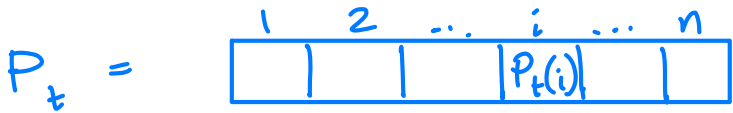
$$= \sum_{x_t} P(x_t) P(X_{t+1} | x_t) \rightarrow \text{factorization}$$

notation 2

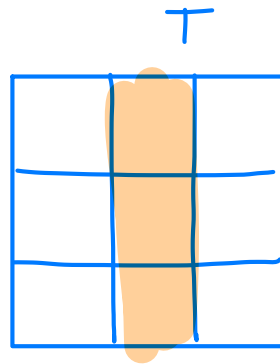
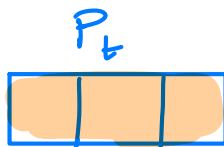
$$P_{t+1}(y) = \sum_x P_t(x) T(x,y) \quad \text{or} \quad P^{(t+1)}(y) = \sum_x P^{(t)}(x) T(x,y)$$

notation 3

$$P_{t+1}(j) = \sum_i P_t(i) \cdot T_{ij} \quad \text{or} \quad P_j^{(t+1)} = \sum_i P_i^{(t)} T_{ij}$$

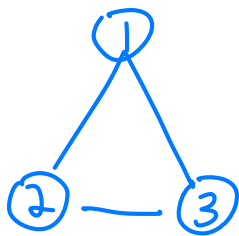


=



← markov matrix  
Each row sum = 1

$$P_{t+1} = P_t T$$



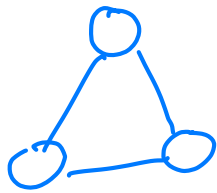
$$P_t = P_0 T^t \longrightarrow \pi$$

$\pi$  stationary distribution

ex.) if other diagonalization

$$\begin{bmatrix} 1 & .99 \\ & -.8 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

ex.)

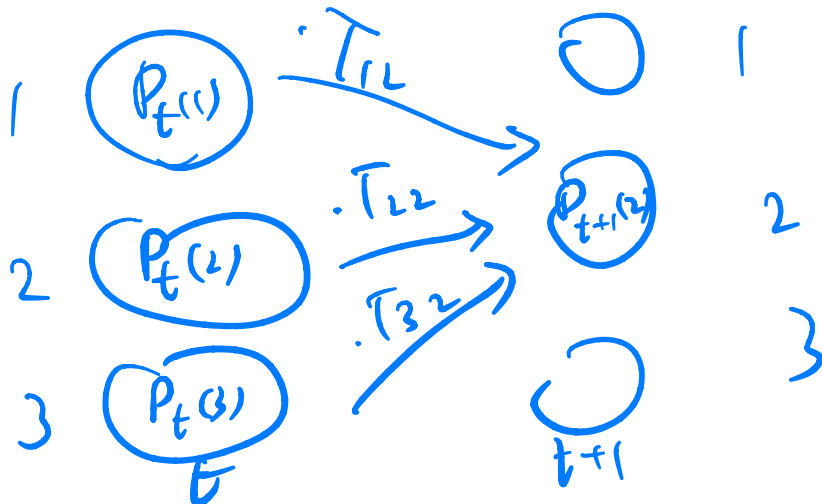


with prob  $\frac{1}{2}$  stay  
with prob  $\frac{1}{4}$  go to one of the remaining 2 states.

$$T = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} \frac{1}{2} & \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} & \frac{1}{2} \end{bmatrix} \end{matrix}$$

Interpret  $P_{t+1}(j) = \sum_i P_t(i) T_{ij}$  :

# people in state  $i$       fraction that go to  $j$



### Multivariate Normal / Gaussian

$$X = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} \sim N(0, \Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix})$$

$\text{Cov}(X_2, X_1)$

$\text{Cov}(X_2, X_2) = \text{Var}(X_2)$

symmetric positive definite

$$[x_2 | x_1] \sim N \left( \Sigma_{21} \Sigma_{11}^{-1} x_1, \Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12} \right)$$

proof:

$$E(x_2 | x_1)$$

$$\text{Var}(x_2 | x_1)$$

$$\varepsilon = x_2 - Ax_1$$

$$x_2 = Ax_1 + \varepsilon \rightarrow \text{like regression}$$

↓  
regression  
coefficient

↓  
regression  
error

we want  $x_1$  to be independent of  $\varepsilon$

$$\text{Cov}(\varepsilon, x_1) = 0$$

$$\begin{aligned} \text{Cov}(x_2 - Ax_1, x_1) &= \text{Cov}(x_2, x_1) - \text{Cov}(Ax_1, x_1) \\ &= \Sigma_{21} - A \Sigma_{11} = 0 \end{aligned}$$

$$A = \Sigma_{21} \Sigma_{11}^{-1}$$

$$\text{Var}(\varepsilon) = \text{Cov}(\varepsilon, \varepsilon) = \text{Cov}(x_2 - Ax_1, \varepsilon)$$

$$= \text{Cov}(x_2, \varepsilon) - \underbrace{\text{Cov}(Ax_1, \varepsilon)}_0$$

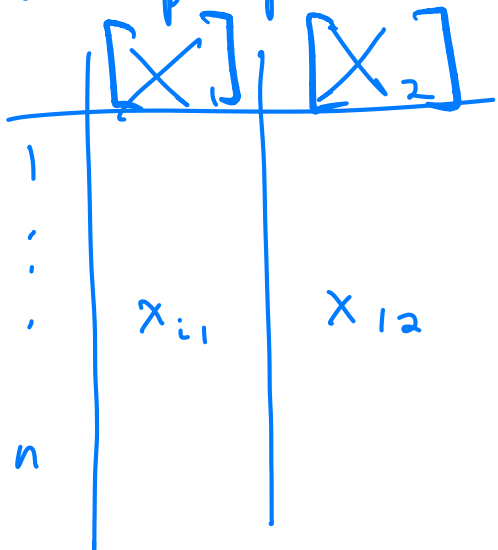
$$= \text{Cov}(x_2, x_2 - Ax_1)$$

$$= \Sigma_{22} - \text{Cov}(x_2, Ax_1)$$

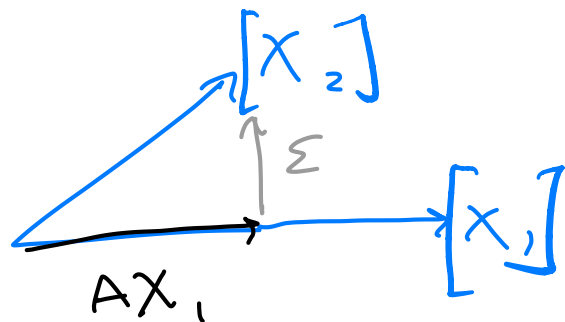
$$= \Sigma_{22} - \text{Cov}(x_2, x_1) A^T$$

$$= \Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12}$$

data perspective



vector perspective



$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \rightarrow \begin{bmatrix} x_1 \\ \epsilon \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 - Ax_1 \end{bmatrix} = \begin{bmatrix} I & 0 \\ -A & I \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{Var} \begin{bmatrix} x_1 \\ \epsilon \end{bmatrix} = \begin{bmatrix} I & 0 \\ -A & I \end{bmatrix} \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix} \begin{bmatrix} I & -AI \\ 0 & I \end{bmatrix}$$

$$= \begin{bmatrix} \Sigma_{11} & 0 \\ 0 & \Sigma_{22} - \Sigma_{21} \Sigma_{11}^{-1} \Sigma_{12} \end{bmatrix}$$

HW\* still need to prove that transformation  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  is still normal.

↳ use change of variable & Jacobian

recall:

$$\text{var}(x) = \Sigma$$

$$\text{var}(Ax) = A \Sigma A^T$$

$$x \sim N(0, \Sigma)$$

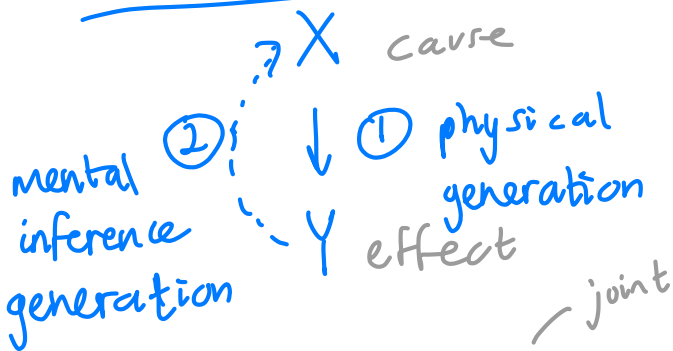
$$y = Ax \sim N(0, A \Sigma A^T)$$

①

use Jacobian

②

# Bayes' Rule



- prior belief  
 prior:  $X \sim p(x)$

generation:  $[Y | X=x] \sim p(y|x)$

posterior:  $[x | Y=y] \sim p(x|y)$   
 ~ updated belief

$$p(x|y) = \frac{p(x,y)}{p(y)}$$

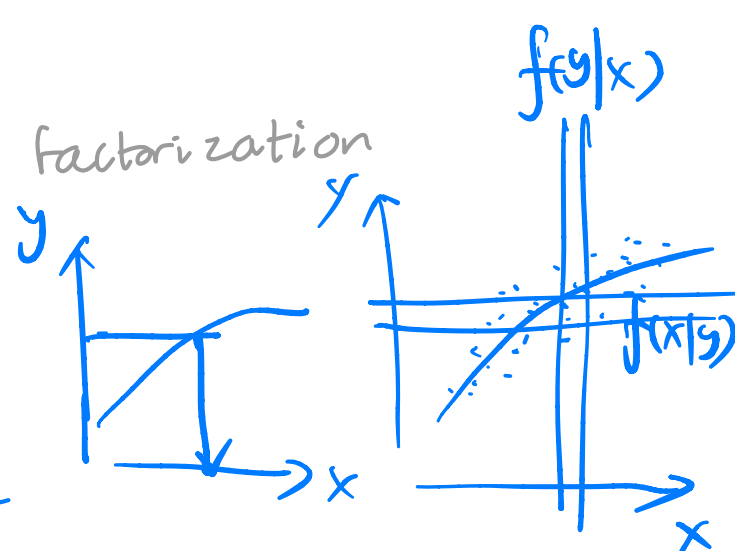
→ conditioning / normalization

$$= \frac{p(x,y)}{\sum_x p(x,y)}$$

→ marginalization

$$= \frac{p(x)p(y|x)}{\sum_{x'} p(x')p(y|x')}$$

→ factorization



ex.) rare disease example

$X$ : discrete       $Y$ : discrete

$X \in \{0, 1\}$   
 0 ↓ no disease      1 ↓ have disease

$x$	0	1
$p(x)$	99%	1%

$Y \in \{+, -\}$

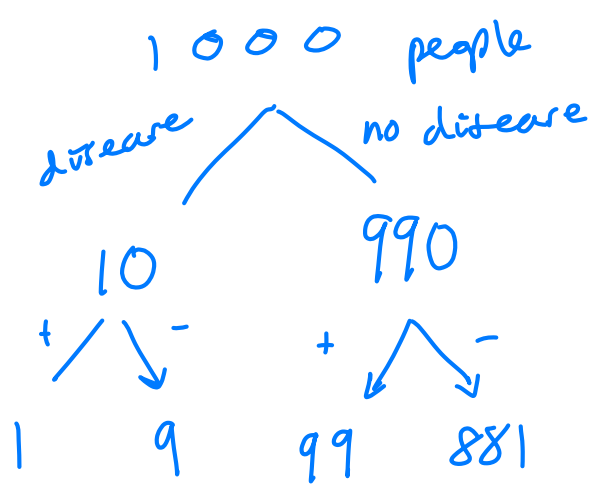
test for disease

$x \backslash y$	0	1
+	10%	90%
-	90%	10%

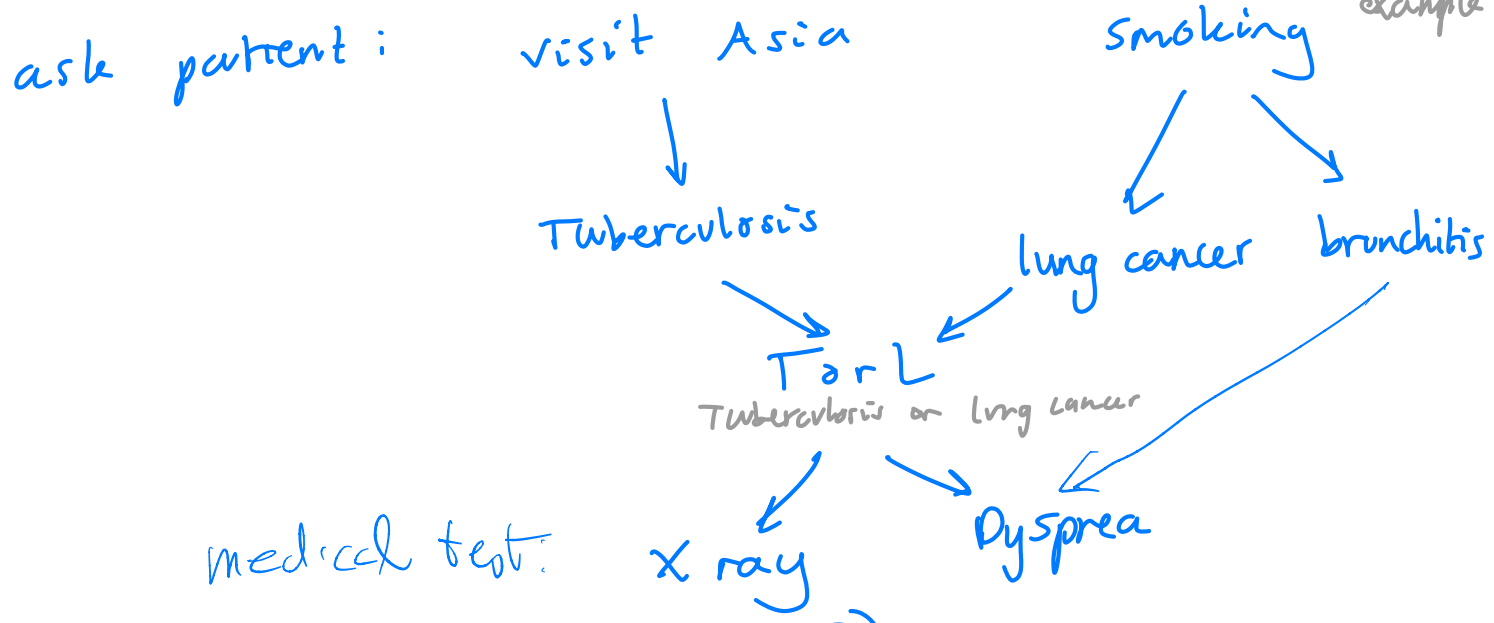
false positive (pointing to the '+' row, '0' column)  
 false negative (pointing to the '-' row, '1' column)

$$P(x^+ | y^+) = \frac{1\% \cdot 90\%}{99\% \cdot 10\% + 1\% \cdot 90\%} = \frac{90}{990 + 90}$$

$$x^+ \in \{0, 1\} = \frac{1}{12}$$



ex.) Asian example



$P(T=1 | X=1, D=0, V=1, S=0)$   
 probability that patient has tuberculosis given that they have a positive x ray, no dyspnea, visit asia, non smoking



$$P(v, s, t, l, b, o, x, d) = p(v)p(s)p(t|v)p(l|s)p(b|s)p(o|t, l) \\ \cdot p(x|o)p(d|o, b)$$

↓  
marginal

factorization

$$P(T=1 | X=1, D=0, V=1, S=0) = p(t|x, d, v, s) \\ = \frac{p(t, x, d, v, s)}{p(x, d, v, s)}$$

conditioning