

Lecture 1



- Topics:

- Regression

- CART, adaboost, XGB

- kernel regression, Gaussian Process, SVM

- Deep learning: MLP, SGD, CNN, RNN, Transformer, GPT, BERT, generative: GAN, VAE, Diffusion

- Reinforcement Learning: MDP, policy, value, AlphaGo, policy gradient, Q-learning, Decision Transformer.

- Coursework:

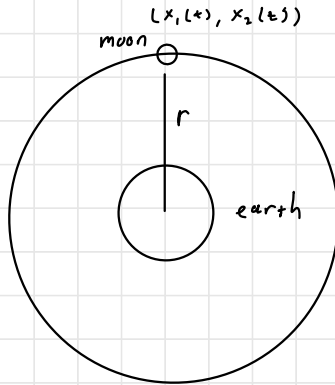
- biweekly hw: coding & theoretical

- coding Python / PyTorch

• Machine Learning in ancient time:

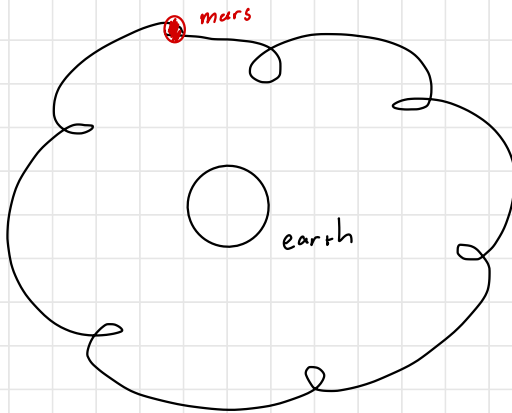
- Astronomy: Observe positions of planets \rightarrow Predict motion

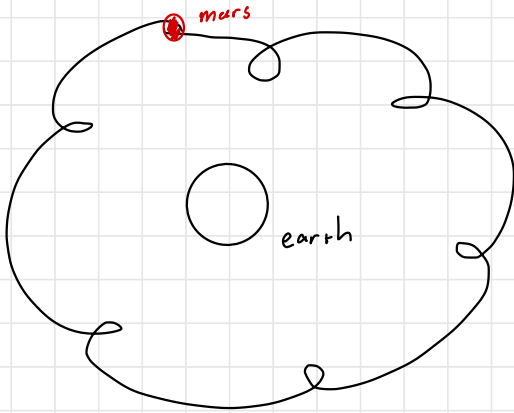
- Ptolemy Epicycle:



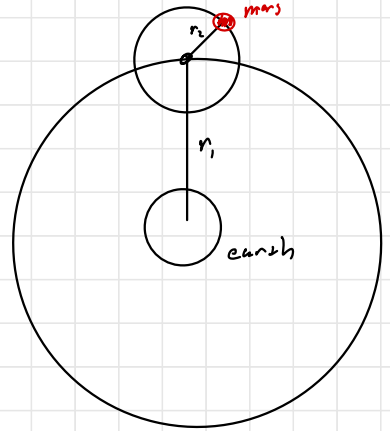
$$X(t) = X_1(t) + i X_2(t)$$

$$= r e^{i\omega t}$$





Ptolemy
 \longrightarrow



$$X(t) = r_1 e^{i\omega_1 t} + r_2 e^{i\omega_2 t}$$

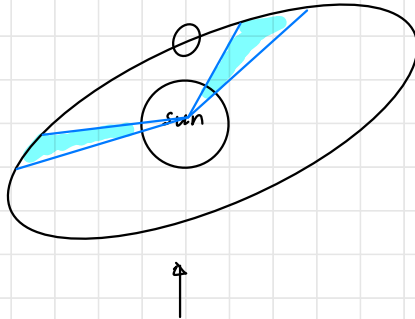
- Then for $r_1 > r_2 > \dots$ we have

$$X(t) = r_1 e^{i\omega_1 t} + r_2 e^{i\omega_2 t} + r_3 e^{i\omega_3 t} + \dots$$

} boosting

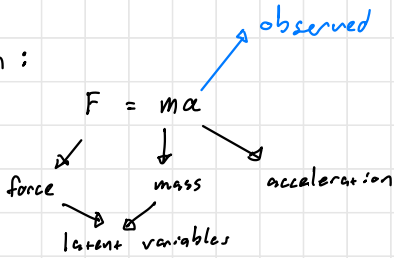
- We can draw an analogy with the MLP, i.e. adding a perceptron on top of a perceptron

- Kepler:



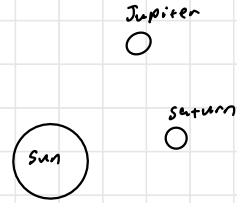
↑
 Simpler model under this re-representation
 But Ptolemy's model is much more general

• Newton:



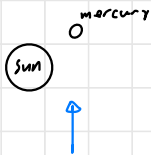
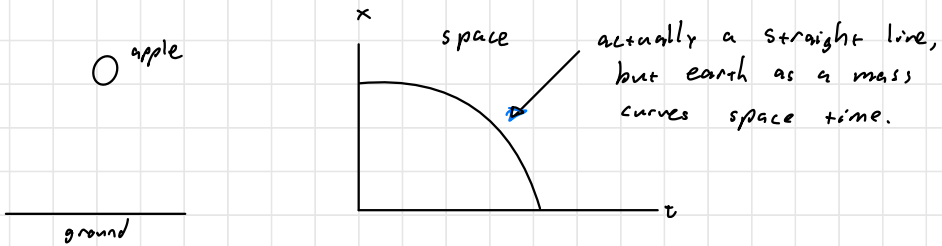
$$F = G \frac{m_1 m_2}{r^2}$$

This is more general.
Can explain 3-Body
interactions.



action at a distance, as real \rightarrow epicycle
(unreal)

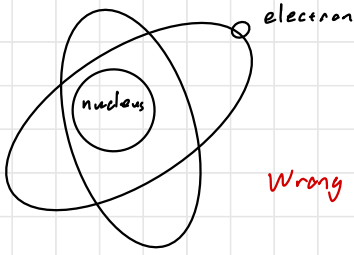
• Einstein:



Einstein can
model this
better than
Newton

} But just as Ptolemy's epicycles are imaginary
so is Einstein's notion of space-time

• Quantum



• Schrodinger:

$$V_{t+\Delta t} = (I + A \Delta t) V_t$$

↓
embedding
(state vector)
thought vector

$A = -i\hbar/H$ Hamiltonian, discrete eigenvalues

∴ Linear RNN
(quantized) (hidden layer)

even more unreal than epicycle

↑ query vector ↑ Key vector

↓ ∴ emission
(output layer)

• Born: $P_e(Lx) \propto |\langle u(Lx), V_e \rangle|^2$

↓
observed state

$\phi_e(Lx)$ ∴ wave function, not a physical wave

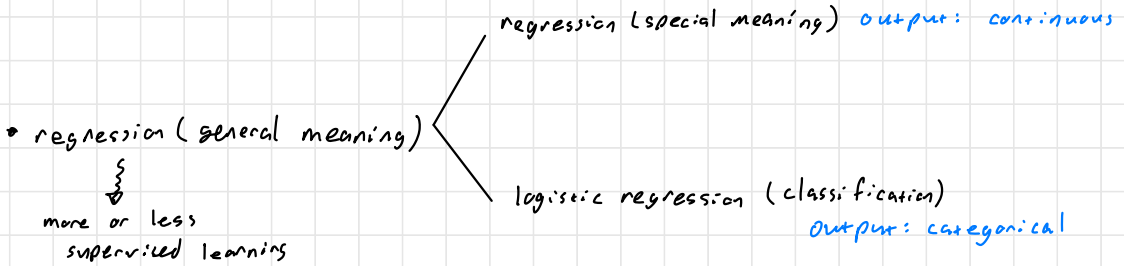
• Bohr, Heisenberg, Pauli: Copenhagen interpretation

observer outside system, collect data from system

Quantum mechanics is not responsible for explaining "reality" beyond observed data

• Machine Learning in Modern Time

- Jan De Leeuw : everything is regression



	input	output
1		
⋮		
⋮		
⋮		
i	x_i	y_i
⋮		
⋮		
n		

• Gauss Paradigm :

- invented Least Squares Method : Used to predict Ceres
- Gauss distribution : maximum likelihood
- Gauss - Markov \rightarrow optimality : LS is the best linear unbiased estimator

• Chat - GPT:

- text: $x_0, x_1, x_2, \dots, x_{t-1}, x_t$ ← tokens (50k of them)

prompt

word
↓

- learn generative model $p(x_t | x_{<t})$, auto-regressive model.

↑ ↑
output input

- $\max_{\theta} \mathbb{E}_{\text{data}} [\log p_{\theta}(x_t | x_{<t})]$ maximum likelihood

The negative of this gives us cross-entropy loss.

→ Similar to a super parrot ~~and~~ Oracle

- Diffusion model:

$$x_0 \longrightarrow \dots \longrightarrow x_t \longrightarrow x_{t+\Delta t} \longrightarrow \dots \longrightarrow x_t$$

$$x_{t+\Delta t} = x_t + \sigma \sqrt{\Delta t} \varepsilon_t, \quad \varepsilon_t \sim \mathcal{N}(0, \mathbf{I})$$

$$\text{learn } p(x_t | x_{t+\Delta t}) \sim \mathcal{N}(f(x_{t+\Delta t}, t), \sigma^2 \Delta t \mathbf{I})$$

$$\max_{\theta} \mathbb{E}_{\text{data}} [\log p_{\theta}(x_t | x_{t+\Delta t})]$$



negative of likelihood gives us
least squares loss.

$$p_{\theta}(x_t | x_{t+\Delta t}, \text{text input}) \longrightarrow \text{generating qpts}$$