

Lecture 15

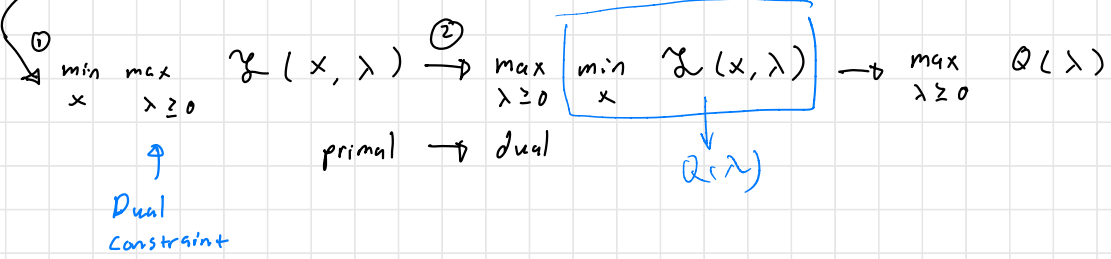


• I.O.V: Constrained Optimization

$$\min f(x)$$

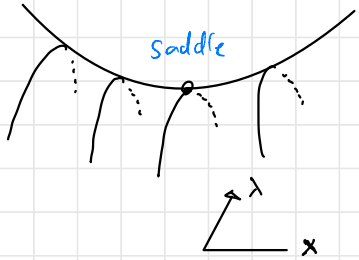
$$\text{s.t. } g(x) \leq 0 \quad \leftarrow \text{primal constraint}$$

$$\mathcal{L}(x, \lambda) = f(x) + \lambda g(x)$$



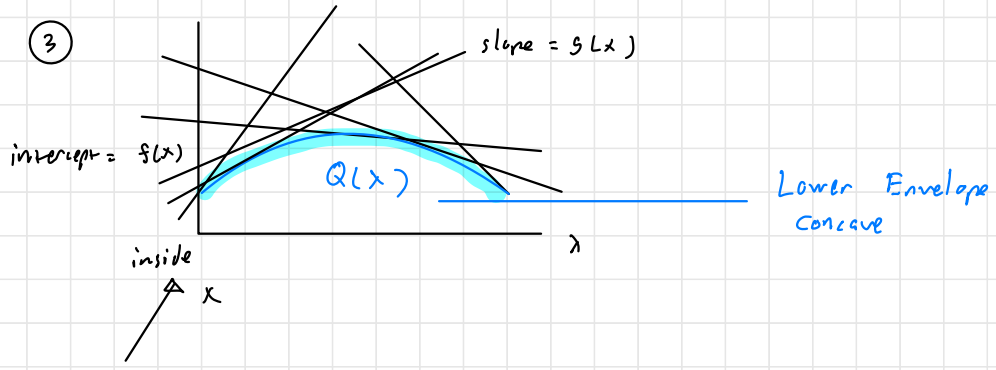
Note: ① $\max_{\lambda \geq 0} \lambda \begin{matrix} g(x) \\ > 0 \end{matrix} \rightarrow \infty$

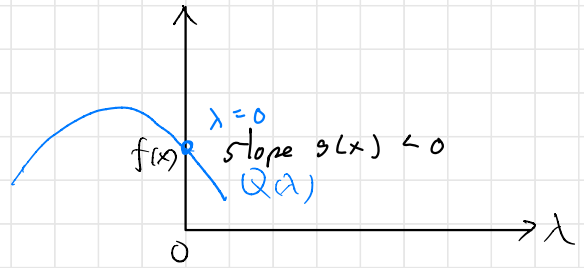
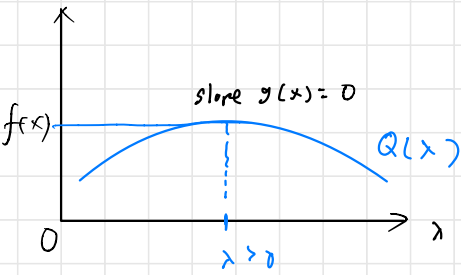
② Von Neumann convex-concave



The Lagrangian is linear in λ

③





What if we had

$$\begin{aligned} \min_x f(x) \\ \text{s.t. } g(x) = 0 \end{aligned}$$

Then no need for $\lambda \geq 0$

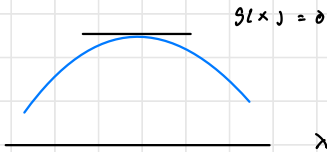
$$\min_x \max_{\lambda} \mathcal{L}(x, \lambda)$$

$$\max_{\lambda} \lambda |g(x)|$$

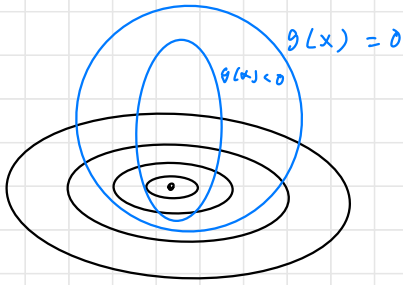
if $g(x) > 0 \xrightarrow{\lambda \rightarrow \infty} +\infty$

if $g(x) < 0 \xrightarrow{\lambda \rightarrow -\infty} +\infty$

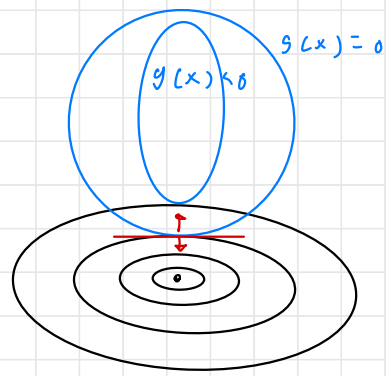
③



- Consider the Contour Plot:



$$\lambda = 0$$



$$f'(x) = -\lambda g'(x)$$

$$f'(x) + \lambda g'(x) = 0$$

$$\frac{\partial}{\partial x} \mathcal{L}(x, \lambda) = 0$$

- KKT conditions

(1) primal constraints

(2) dual constraints

(3) stationarity $\frac{\partial}{\partial x} \mathcal{L} = 0$

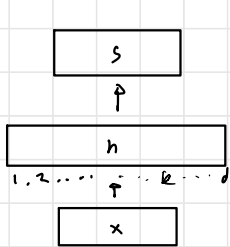
(4) complementary slackness: $\lambda g(x) = 0$

• Deep Learning :

- slogan 1: approximator

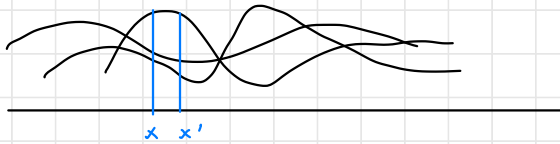
- ReLU : $f(x)$ piecewise linear

- Sigmoid : $f(x)$ piecewise constant



$$s = f(x) = \frac{1}{\sqrt{d}} \sum_{k=1}^d \beta_k \sigma(x^T \alpha_k)$$

• Initialization : $\begin{pmatrix} \alpha_k \\ \beta_k \end{pmatrix} \stackrel{iid}{\sim} p_0(\alpha_k, \beta_k), k=1, \dots, d$



$$k(x, x') = \text{cov}(f(x), f(x')) = \text{cov}\left(\frac{1}{\sqrt{d}} \sum \beta_k \sigma(x^T \alpha_k), \frac{1}{\sqrt{d}} \sum \beta_{k'} \sigma(x'^T \alpha_{k'})\right)$$

$$= \frac{1}{d} \sum_{k=1}^d E(\beta_k^2 \sigma(x^T \alpha_k) \sigma(x'^T \alpha_k))$$

$$= E(\beta_k^2 \sigma(x^T \alpha_k) \sigma(x'^T \alpha_k)) \quad \text{Central Limit Theorem}$$

so $f(x) \sim \text{NNGP}(\quad) \xrightarrow{d \rightarrow \infty}$ CLT converges to GP

Neural net Gaussian process

1. Gradient Descent Learning

- freeze α_{1k} $\ddot{y}^d P_0(\alpha)$

$$f(x) = h(x)^T \beta$$

$$h_{1k} = \frac{1}{\sqrt{d}} \sigma(x^T \alpha_{1k}) \quad \text{random feature}$$

learn β

$$\text{Loss}(\beta) = \frac{1}{2n} \sum_{i=1}^n (y_i - h(x_i)^T \beta)^2$$

$$\beta_0 = 0$$

$$\beta_{t+1} = \beta_t + \eta_t \frac{1}{n} \sum_{i=1}^n (y_i - h(x_i)^T \beta_t) h(x_i)$$

e_i

$$\longrightarrow \hat{\beta} = \sum_{i=1}^n c_i h(x_i) \quad \text{representer.}$$

$$\hat{f}(x) = h(x)^T \hat{\beta} = \sum_{i=1}^n c_i \langle x_i, x \rangle \quad \text{kernel regression}$$

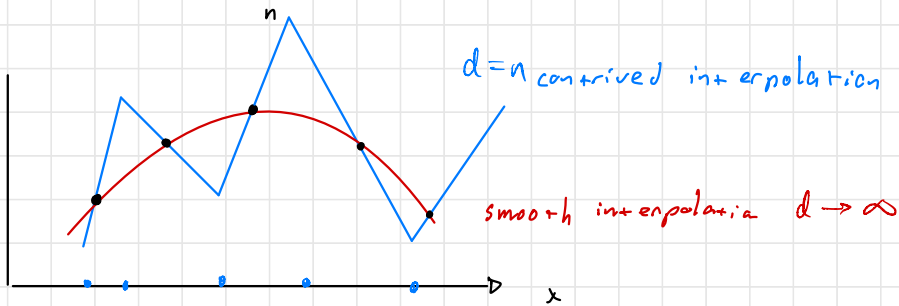
$\lambda \rightarrow 0$

\downarrow
query

• Over parameterization: $d \rightarrow \infty$

- Double Descent

Error



- Consider unfreeze $\alpha_{ik} \stackrel{iid}{\sim} p_0(\alpha)$

$$\theta = \{ \theta_{ik} = (\alpha_{ik}, \beta_{ik}) , k = 1, \dots, d \}$$

initialization $\theta_{ik}^0 = (\alpha_{ik}^0, \beta_{ik}^0) \sim p_0(\alpha, \beta)$

$$f_{\theta}(x) = f_{\theta_0}(x) + \langle \theta - \theta_0, \nabla_{\theta} f_{\theta_0}(x) \rangle + 2^{nd} \text{ order}$$

↓
query
fixed

$$f_{\theta}(x) = \frac{1}{\sqrt{d}} \sum_{k=1}^d \beta_k \sigma(x^T \alpha_k) = \frac{1}{\sqrt{d}} \sum_{k=1}^d h_{\theta_k}(x)$$

$$= f_{\theta_0}(x) + \frac{1}{\sqrt{d}} \sum_{k=1}^d \nabla_{\theta_k} h_{\theta_k^0}(x) (\theta_k - \theta_k^0) + \frac{1}{2} \frac{1}{\sqrt{d}} \sum_{k=1}^d \nabla_{\theta_k}^2 h_{\theta_k^0}(x) (\theta_k - \theta_k^0)^2$$

$$\Delta = f_{\theta}(x) - f_{\theta_0}(x) \text{ so } (\theta_k - \theta_k^0) \propto \frac{1}{\sqrt{d}} \text{ perturbation } \downarrow 0$$

$$\text{also } (\theta_k - \theta_k^0)^2 \propto \frac{1}{d}$$

Thus the second term $\rightarrow 0$

Note: As $d \rightarrow \infty$ The model behaves as a linear model
(Tangent Model)

$$f_{\theta}(x) = f_{\theta_0}(x) + \underbrace{\langle \theta - \theta_0, \nabla_{\theta} f_{\theta_0}(x) \rangle}_{\tilde{h}(x)} + \text{2nd order}$$

Neural Tangent Kernel Regime

$$\langle \tilde{h}(x), \tilde{h}(x') \rangle = \frac{1}{d} \sum_{k=1}^d \nabla_{\theta_k} h_{\theta_k^0}(x) \cdot \nabla_{\theta_k} h_{\theta_k^0}(x')$$

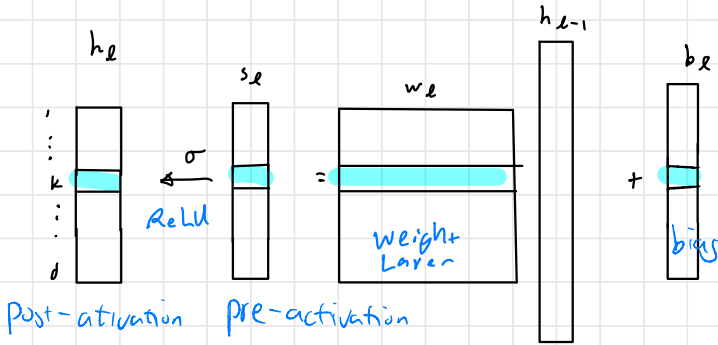
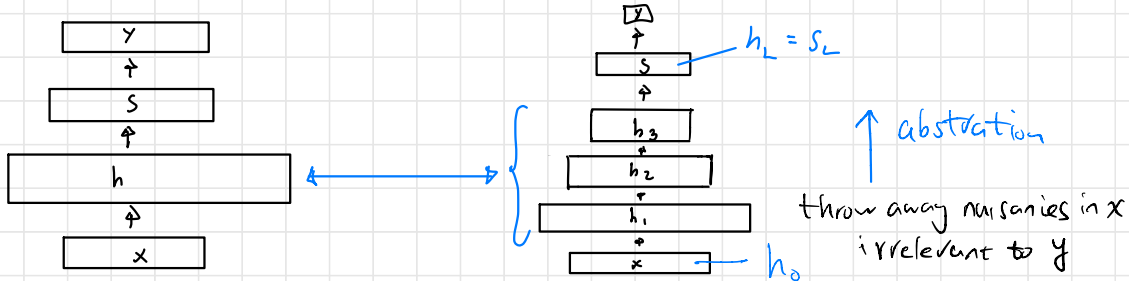
$$\rightarrow \mathbb{E}_{\theta_k} (\quad)$$

Law of large #

• Multi-Layer Perceptron (MLP)

Recall :

MLP :



$$h_{l,k} = \sigma(s_{l,k})$$

$$s_l = w_l h_{l-1} + b_l \Rightarrow s_{l,k} = w_{l,k} h_{l-1} + b_{l,k}$$

$$\Theta = (w_l, b_l, l=1, \dots, L)$$

• Regression: $Loss = \frac{1}{2} |y - s|^2$

$$\begin{matrix} | \\ | \end{matrix}$$

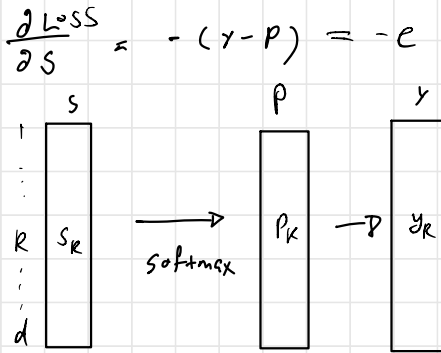
$$\frac{\partial Loss}{\partial s} = -(y - s) = -e$$

• Classification:

$$P(y|s) = \frac{e^{\langle y, s \rangle}}{Z} = \frac{e^{y_k s_k}}{\sum_{c=1}^C e^{y_c s_c}}$$

$$\begin{matrix} | \\ \vdots \\ k \\ \vdots \\ c \end{matrix} \begin{matrix} | \\ \vdots \\ s_k \\ \vdots \\ s_c \end{matrix}$$

$Loss = -\log P(y|s)$ cross-entropy



generalized linear model
(GLM)

• Error back-prop

Loss

⋮

↓

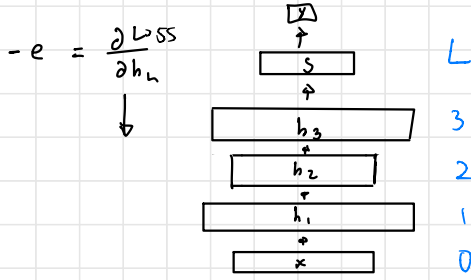
$$\frac{\partial \text{Loss}}{\partial h_L} \rightarrow \frac{\partial \text{Loss}}{\partial w_L}, \frac{\partial \text{Loss}}{\partial b_L}$$

↓

$$\frac{\partial \text{Loss}}{\partial h_{L-1}}$$

↓

⋮



$$-e = \frac{\partial \text{Loss}}{\partial h_L}$$

$$\frac{\partial \text{Loss}}{\partial h_{L-1}^T} = \sum_{k=1}^d \frac{\partial \text{Loss}}{\partial h_{L,k}} \cdot \frac{\partial h_{L,k}}{\partial s_{L,k}} \cdot \frac{\partial s_{L,k}}{\partial h_{L-1}^T}$$

$$= \sum_{k=1}^d \frac{\partial \text{Loss}}{\partial h_{L,k}} \sigma'_k(s_{L,k}) w_{L,k}$$

$$= \begin{pmatrix} \dots & \frac{\partial \text{Loss}}{\partial h_{L,k}} & \dots \\ 1 & \dots & k & \dots & d \end{pmatrix} \begin{pmatrix} \vdots \\ \sigma'_k(s_{L,k}) w_{L,k} \\ \vdots \end{pmatrix} \begin{matrix} 1 \\ \vdots \\ k \\ \vdots \\ d \end{matrix}$$

$$= \frac{\partial \text{Loss}}{\partial h_L^T} \sigma_L' \odot w_L$$

↓
non-wise multiply

$$\sigma_L' = \begin{pmatrix} \sigma'_k(s_{L,k}) \\ \vdots \\ \sigma'_k(s_{L,k}) \end{pmatrix} \begin{matrix} 1 \\ \vdots \\ k \\ \vdots \\ d \end{matrix}$$

$$\frac{\partial \text{Loss}}{\partial w_{L,k}} = \frac{\partial \text{Loss}}{\partial h_{L,k}} \frac{\partial h_{L,k}}{\partial s_{L,k}} \cdot \frac{\partial s_{L,k}}{\partial w_{L,k}}$$

$$= \frac{\partial \text{Loss}}{\partial h_{L,k}} \sigma'_k(s_{L,k}) h_{L-1}^T$$

$$= \frac{\partial \text{Loss}}{\partial w} = \begin{pmatrix} \frac{\partial \text{Loss}}{\partial w_{2,k}} \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{pmatrix} = \begin{pmatrix} \sigma'(L_{2,k}) \frac{\partial \text{Loss}}{\partial h_{2,k}} \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{pmatrix} h_{2-1}^T =$$

$$= \sigma_2' \odot \frac{\partial \text{Loss}}{\partial h_2} \cdot h_{2-1}^T$$